# On the Pitfalls of Geographic Face Routing

#### **Referent:**

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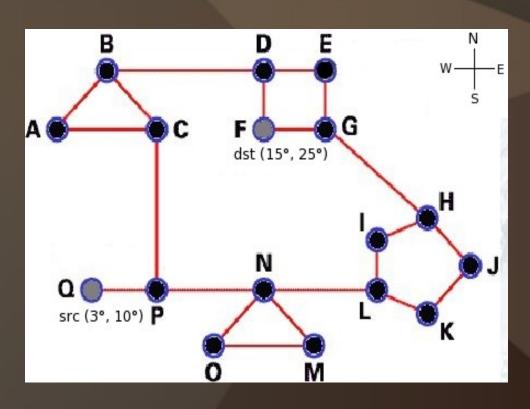
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This presentation is based on the content of the following scientific publication — On the Pitfalls of Geographic Face Routing, 2005, Authors: Young-Jin Kim, Ramesh Govindan, Brad Karp, Scott Shenker

### Outline

- Introduction
- Planarization
- Face Traversal
- Practical Experiments
- Conclusion

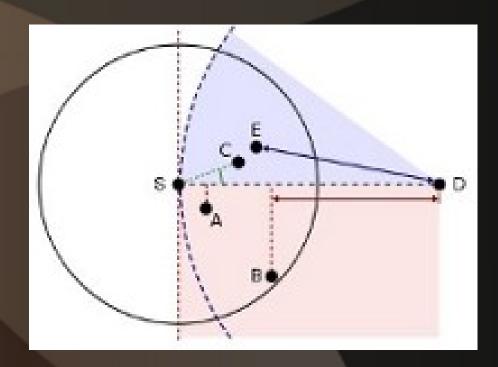
## Geographic Routing?



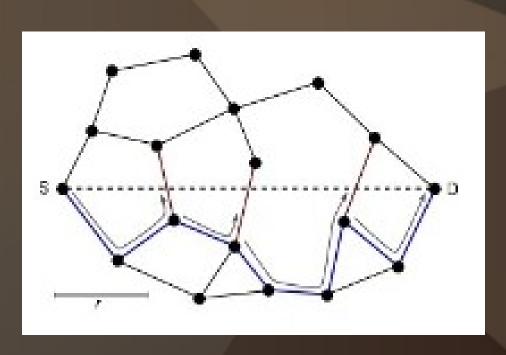
- Network address <u>not</u> <u>used</u>
- Routing is done via geographical coordinates of the nodes
- Various algorithms

## Greedy Overview

 Greedy forwarding tries to bring the message closer to the destination in each step using only local information



## Face Routing Overview



 A message is routed along the interior of the faces of the communication graph, with face changes at the edges crossing the S-D-line. The final routing path is shown in blue.

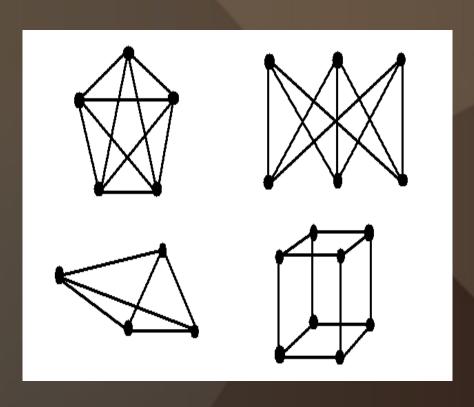
## Combined Approach

- 1. Use "Greedy" and try to reach destination
- 2. If got stuck then use "Face Routing"
- 3. If "first closure" occurred then go to 1
- Implementing protocols: GFG, GPSR, GOAFR+
- Main blocks: Greedy, Planarization, Face traversal

## Paper Overview

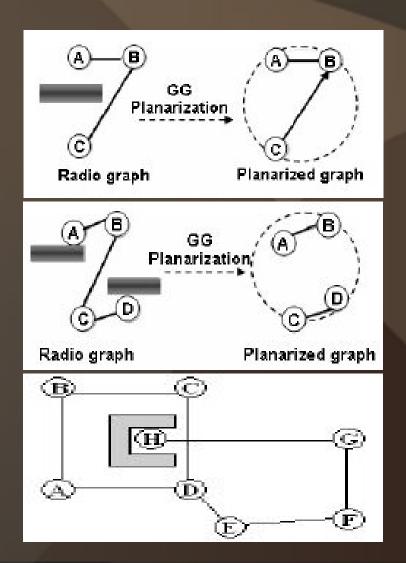
- Definition of weakest points of Geographic Routing protocols
- Classification of failure situations in common approaches
- Measurement of pathologies caused by failures
- Suggestions for increase of routing success rate
- Practical experiments proving efficiency of suggested approaches

## Planarization in detail



- Common algorithms: GG, RNG, RDG
- Main idea: eliminate cross links via "witnesses" lying in a fixed geometric region
- Strictly rely on unit-disk graph assumption

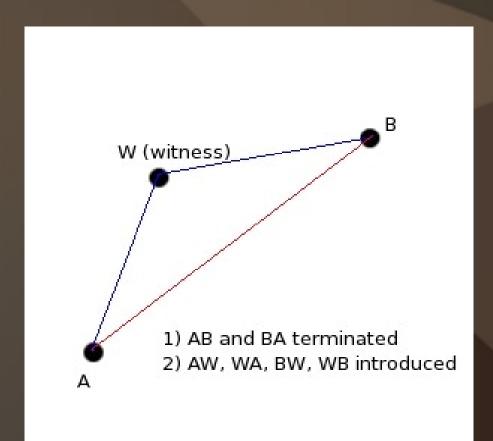
## Planarization failure cases



 Reasons: radio blocking obstacles, incorrect self location estimate etc

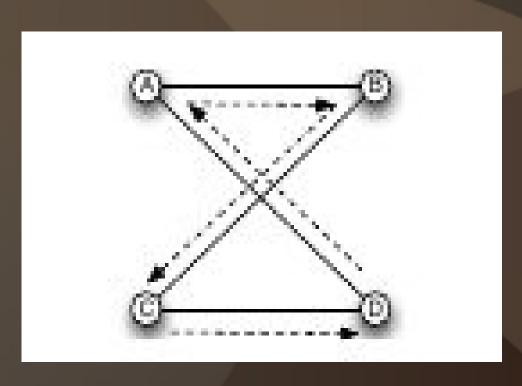
- Arising problems:
  - Unidirectional links
  - Disconnected links
  - Cross links

#### Mutual Witness Procedure



- Communication between nodes by sending lists of the neighbors in order to identify mutual ones
- Just slightly increases efficiency of the protocol

#### Cross Link Detection Protocol

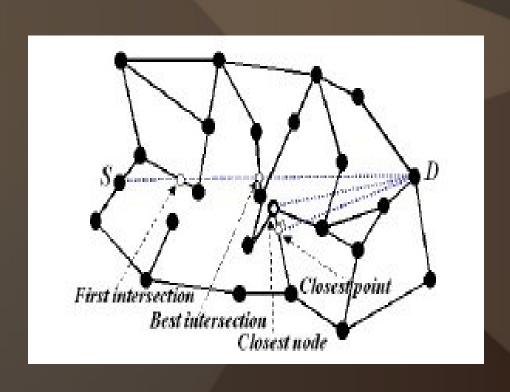


- Idea: send "probe" to travel the graph in order to detect cross links, since it can be checked whether probe has been in one point two times during travel
- Each link of each node must be checked

#### CLDP vs. MWP

- CLDP theoretically eliminates all cross links and has showed 100% efficiency during experiments on topology with 23 and 50 static nodes
- CLDP doesn't solve the collinear links problem
- MWP can leave some cross links in sub-graph and showed rather poor performance of 87.8% leaving some nodes disconnected
- MWP can convert some cross links into collinear ones

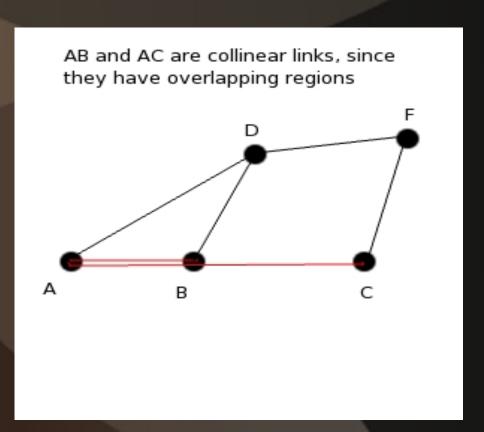
#### Face Traversal in detail



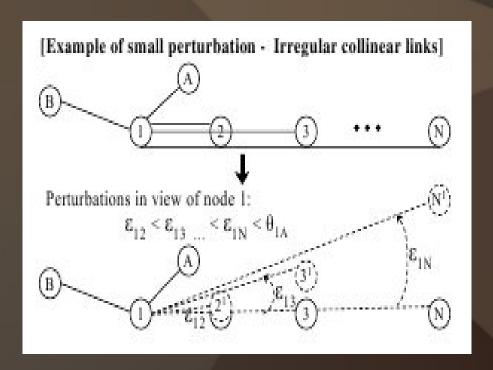
- Algorithms: Best Intersection, First Intersection, Closest-Node, Closest-Point
- Only Best Intersection and Closest-Point guarantee correct results

#### Collinear links

- Links that have overlapping regions with one or more other links
- Introduce difficulty for right-hand rule to change face



## Small perturbations of node positions



- Modify node positions at another endpoint in such way that links move counterclockwise.
- Should be done for all collinear links using different angles

## Improved right-hand rule

- When links are collinear it is unclear whether the angle between them is 0 or  $2\pi$
- If packet came from collinear link "a" which is shorter than current collinear link "b" then angle is considered to be 0, otherwise  $2\pi$
- If there are several collinear links to travel from the current one then the one with the minimal length is chosen as a next hop

# Small perturbations vs. Improved right-hand rule

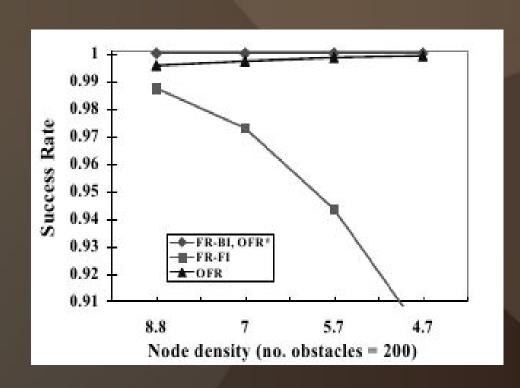
 Small perturbations approach requires very small values of rotation angles, which is not always practically achievable

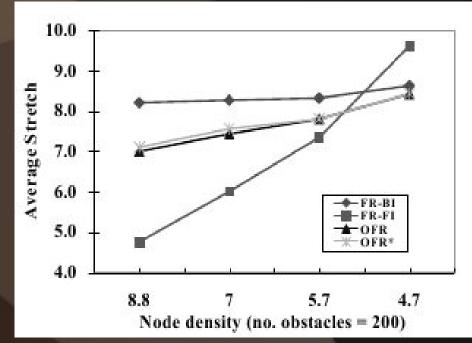
• Improved right-hand rule seems to show the equivalent results as the aforementioned approach, but doesn't require any small values thus not introducing difficulties in implementation

## Experiments overview

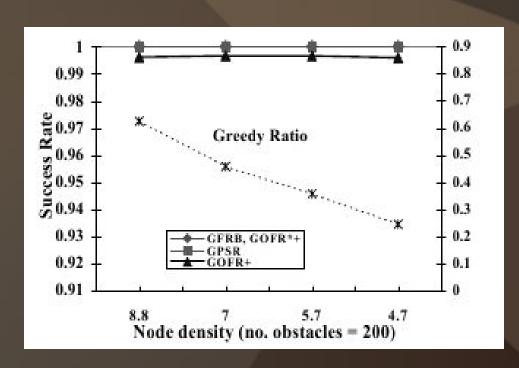
- Environment: 200 radio-opaque obstacles, random node position generation
- Results are mean values between 50 experiments
- Success rate indicates the percentage of successfully delivered packets
- Average stretch indicates the number of hops between source and destination divided by minimal number of hops in optimal path

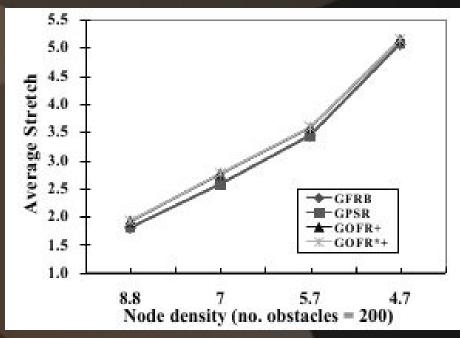
## Table of results (face change rules)





## Table of results (protocols)





## Results discussion

- Face Traversal algorithms with the highest success rate(100%) – Best Intersection, Closest-Point
- Protocols with the highest success rate(100%) GFRB(Greedy + Best Intersection), GPSR(Greedy
  + First Intersection), GOFR\*+(Greedy + ClosestPoint)
- Average stretch is almost equal in all of the algorithms due to usage of Greedy

### Conclusion

- Robust Geographic Routing is practically achievable
- Theoretical researches and practical experiments have shown that best results were achieved through using CDLP for cross link elimination, Improved right-hand rule for collinear links elimination and Best-Intersection/Closest-Point for successful face change

## References

- 1. http://en.wikipedia.org/wiki/Geographic\_routing, 2009-12-18
- 2. On the Pitfalls of Geographic Face Routing. Y.-J. Kim, R. Govindan, B. Karp, S. Shenker, 2005
- 3. Geographic Routing Made Practical. Y.-J. Kim, R. Govindan, B. Karp, S. Shenker, 2005

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- Some of the pictures in this presentation were taken from
  - http://www.etsu.edu/math/gardner/5025/platonic/p lanar.bmp, 12.02.2010
  - http://en.wikipedia.org/wiki/Geographic\_routing, 2009-12-18
  - http://richardwiseman.files.wordpress.com/2009/0 5/question-mark3a.jpg
  - On the Pitfalls of Geographic Face Routing. Y.-J. Kim, R. Govindan, B. Karp, S. Shenker, 2005

# Thank you for your attention

#### Questions

