

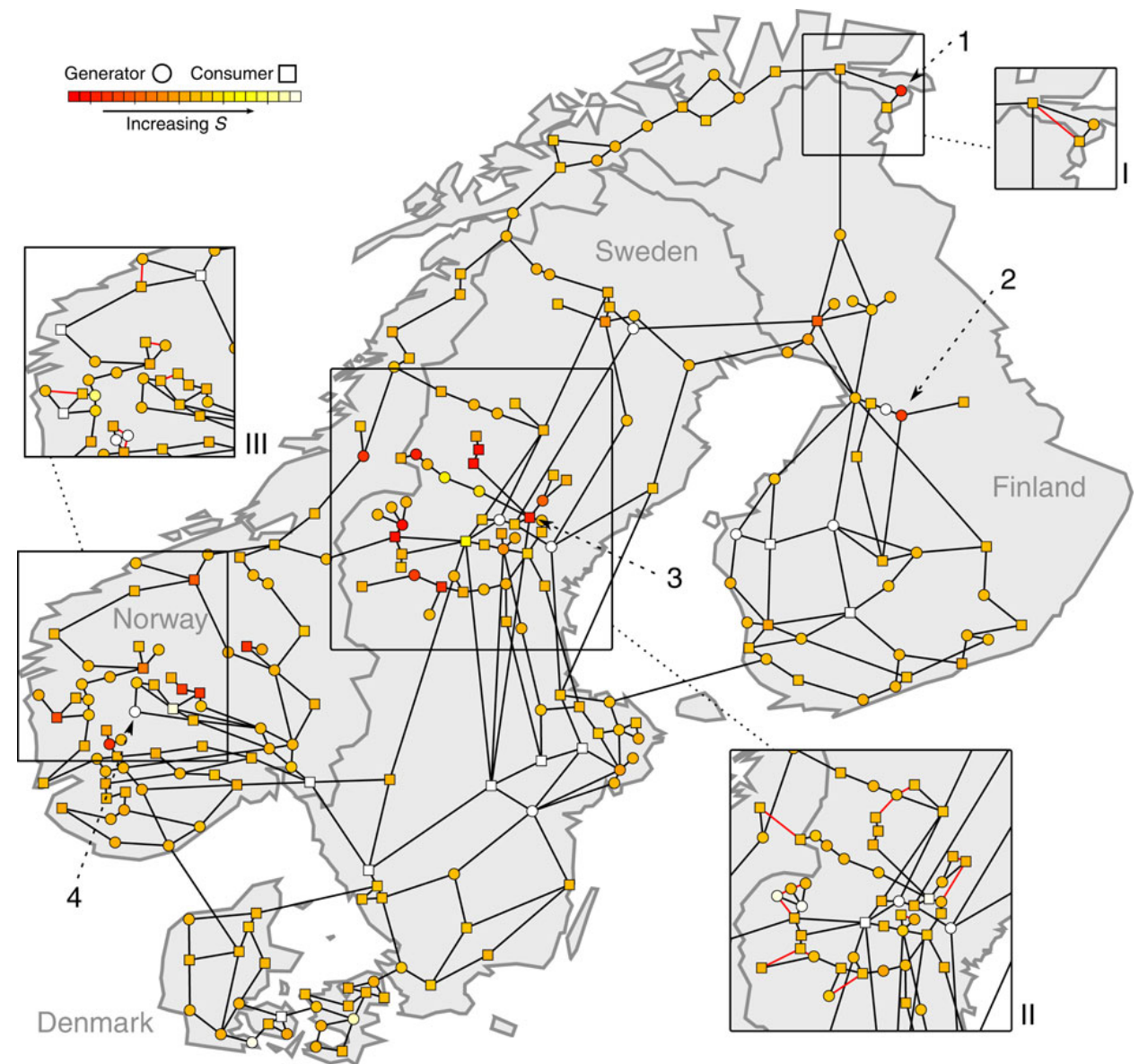
Energy Informatics

03 Network Algorithms

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Graph Theory in a Nutshell

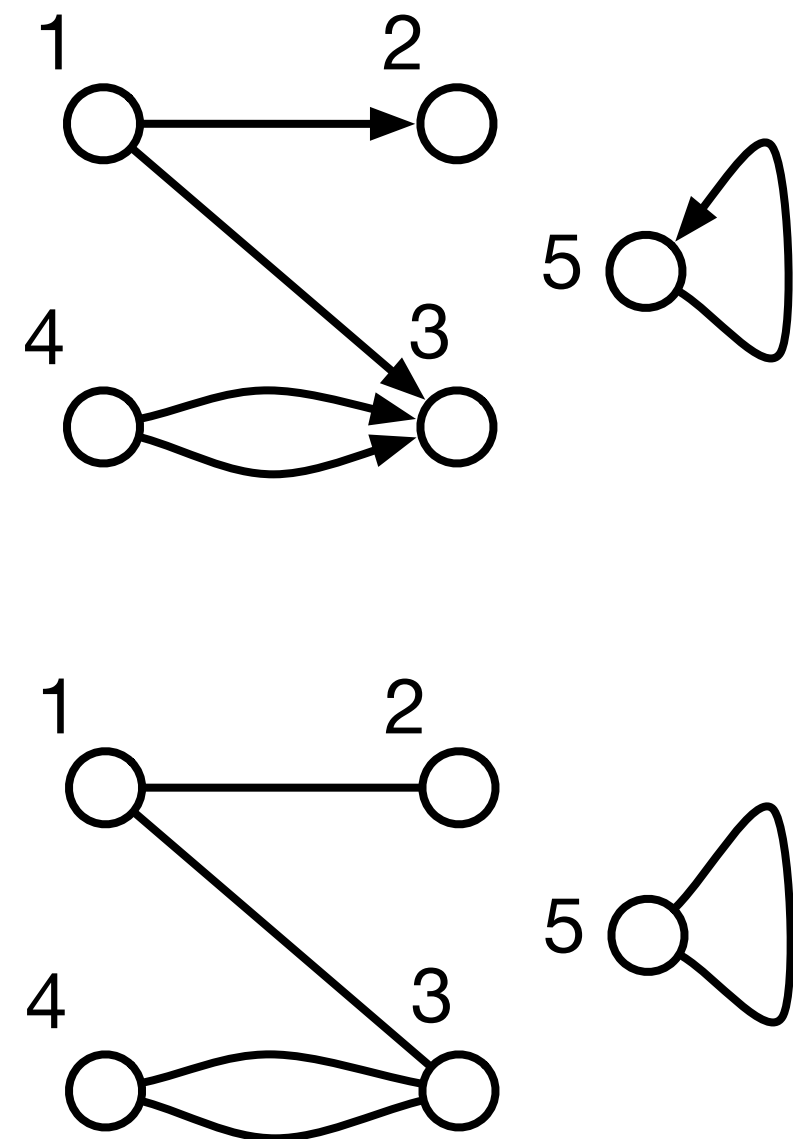
- A graph $G=(V,E)$
 - nodes/vertices V
 - edges E
 - connecting two nodes
- Variants
 - undirected/directed edge
= lines/arrows
 - loops
 - edge connecting the node with itself
 - node/edge weights
 - mapping of numbers to the nodes/edges



How dead ends undermine power grid stability
 Peter J. Menck, Jobst Heitzig, Jürgen Kurths & Hans Joachim Schellnhuber
 Nature Communications 5, Article number: 3969

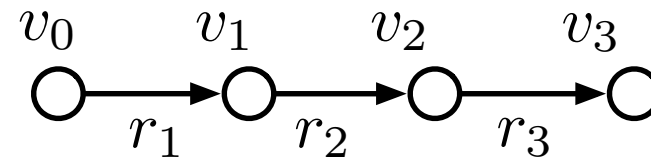
Terms in Graphs

- Degree of a node
 - number of edges at a node u
- Regular graph
 - if the maximum degree = minimum degree in a graph
- Indegree/Out-degree
 - in case of directed graph (digraph), the number of edges pointing to/from a node u
- Two nodes u, v are **adjacent**
 - if they are connected via an edge
- A graph is simple, if there are no loops or no parallel edges
 - usually only simple graphs are considered

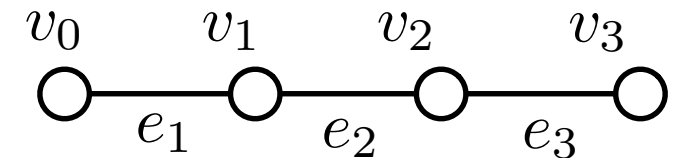


- A sequence of adjacent nodes is called a path
- Paths with same start and end are called cycles
- The length of a path is the number of edges passed
- A path is simple if no edge occurs twice
 - it is elementary if no node occurs twice

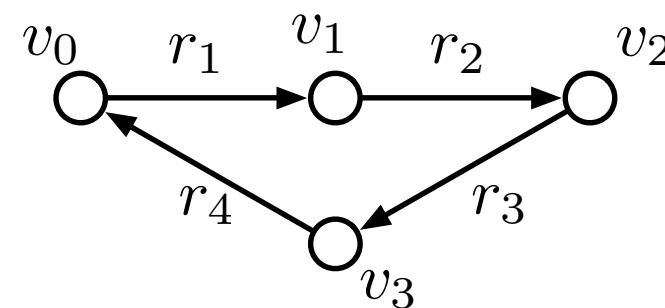
path of length 3



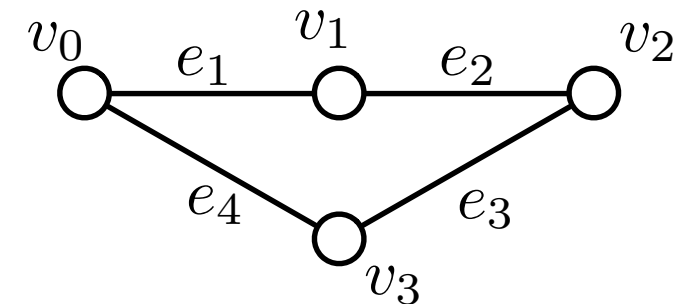
path of length 3



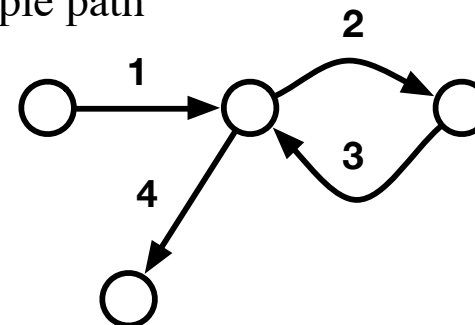
cycle of length 4



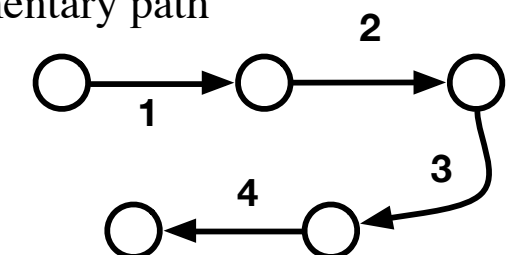
cycle of length 4



walk
simple path

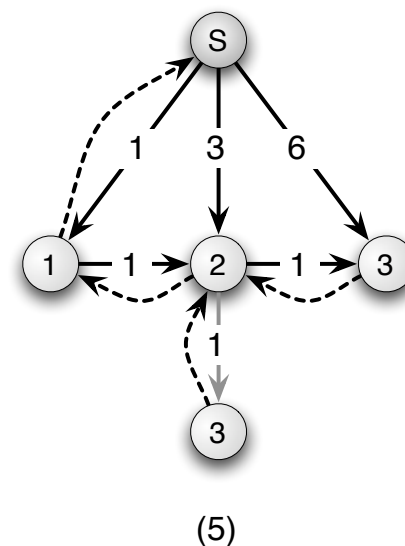
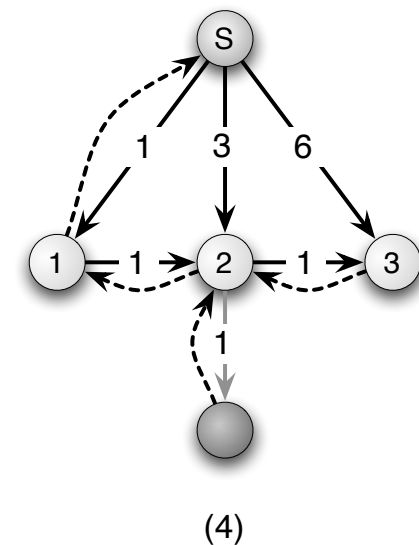
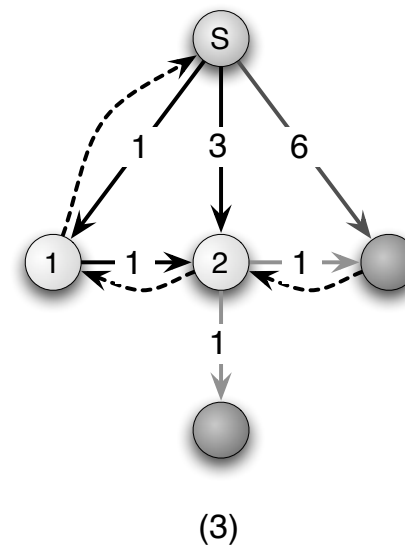
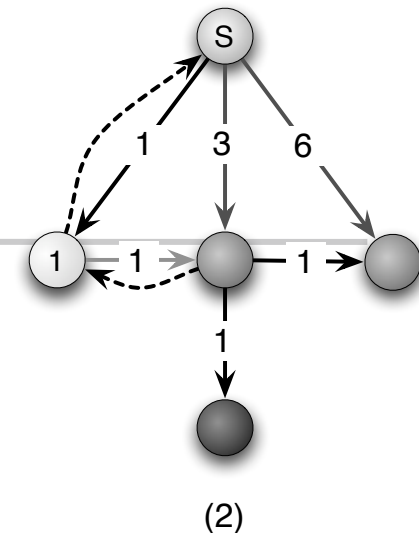
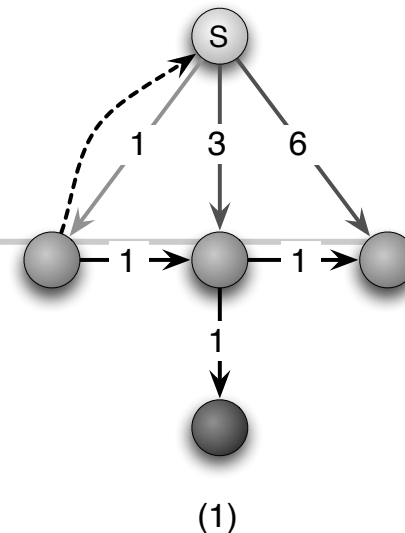


trail
elementary path

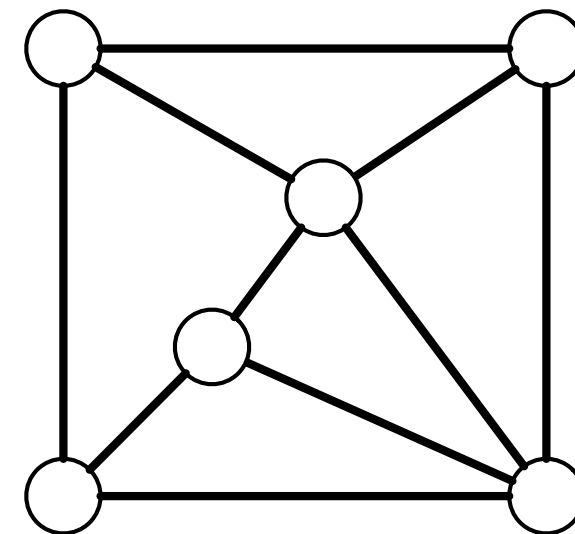
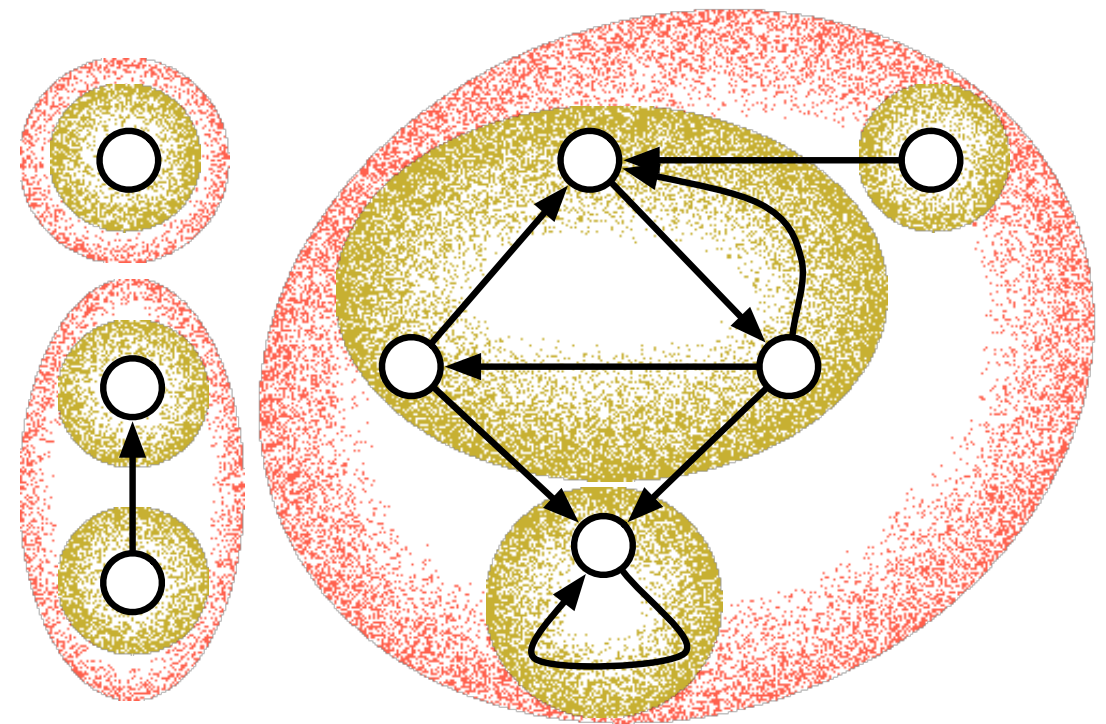


Shortest Paths

- Given
 - a graph $G=(V,E)$
 - start node s , target node t
- Compute the shortest path
- Dijkstras algorithm
 - Start with set $S=\{s\}$
 - In each round
 - add the node u of the neighborhood of S
 - which has the shortest distance to s
 - store the edge used to u



- An undirected graph is **connected**
 - if for all nodes u, v there exists a path connecting u and v
- A directed graph is **weakly connected**
 - if the corresponding undirected graph is connected
- A directed graph is **strongly connected**
 - if for all nodes u, v there exists a directed path connecting u and v
- A graph is **k -(vertex)-connected**, if there are k node disjoint paths between all nodes
- analog definition for d -edge connected



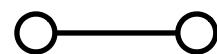
Special Graphs

- Complete (simple) undirected graphs

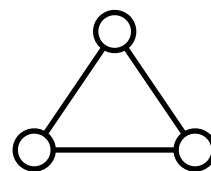
- no. of edges is $n(n-1)/2$



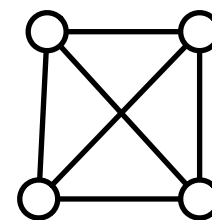
K_1



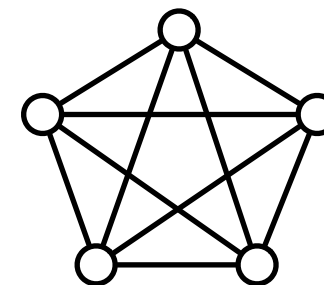
K_2



K_3



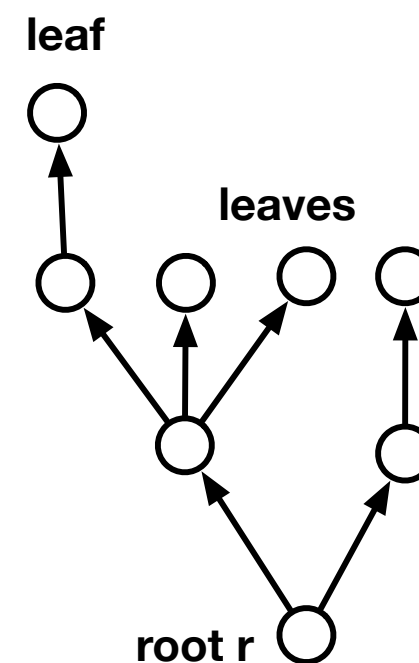
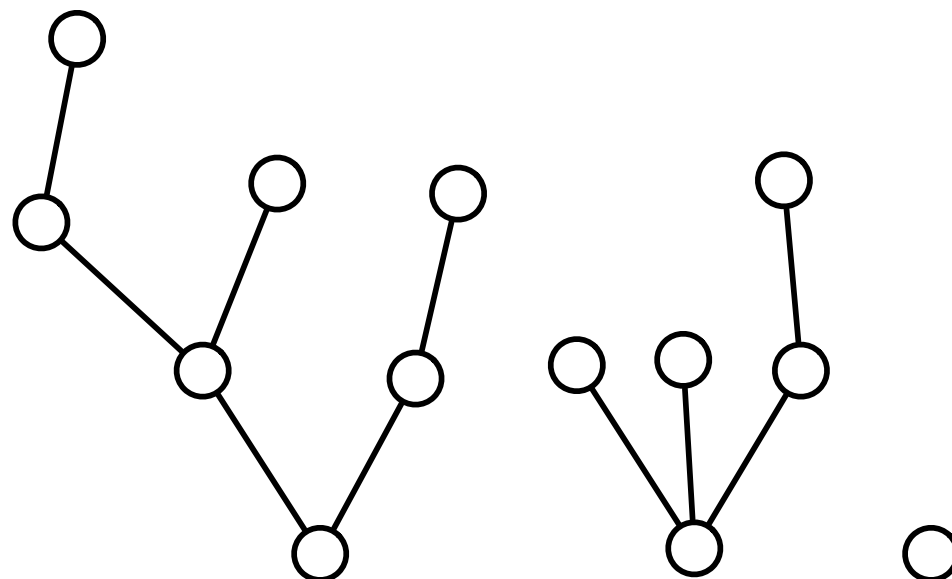
K_4



K_5

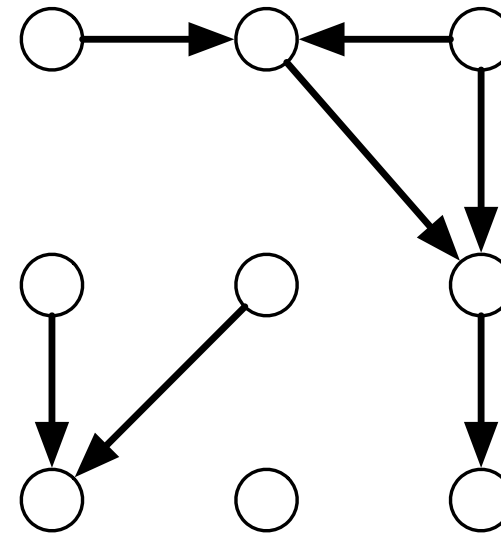
- Trees are connected undirected graphs without cycles

- sets of graphs are called forests

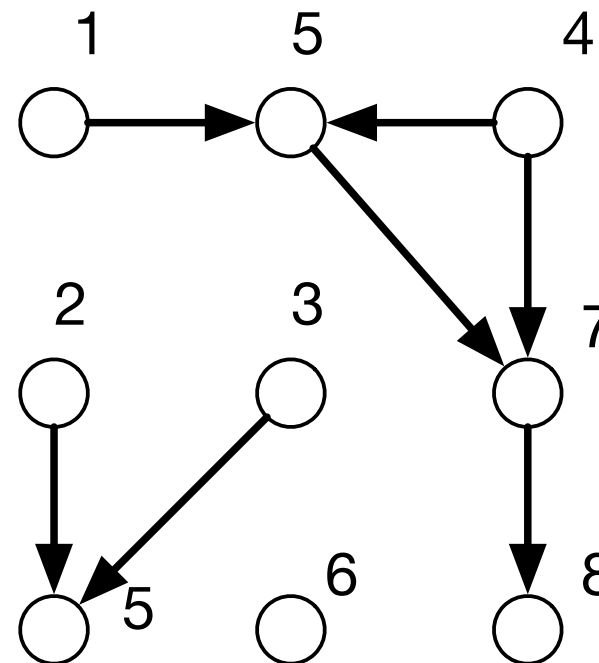


DAG: Directed Acyclic Graph

- Directed acyclic graph



- Topologic Sorting
 - mapping f of $\{1, \dots, n\}$ to V such that for edge (u, v)
 - $f(u) < f(v)$



■ Motivation

- Optimize flow from source to target

■ Definition:

- (Single-commodity) maximum flow problem
- Given

- a graph $G=(V,E)$
- a capacity function $w:E \rightarrow \mathbb{R}_0^+$,
- source set S and target set T

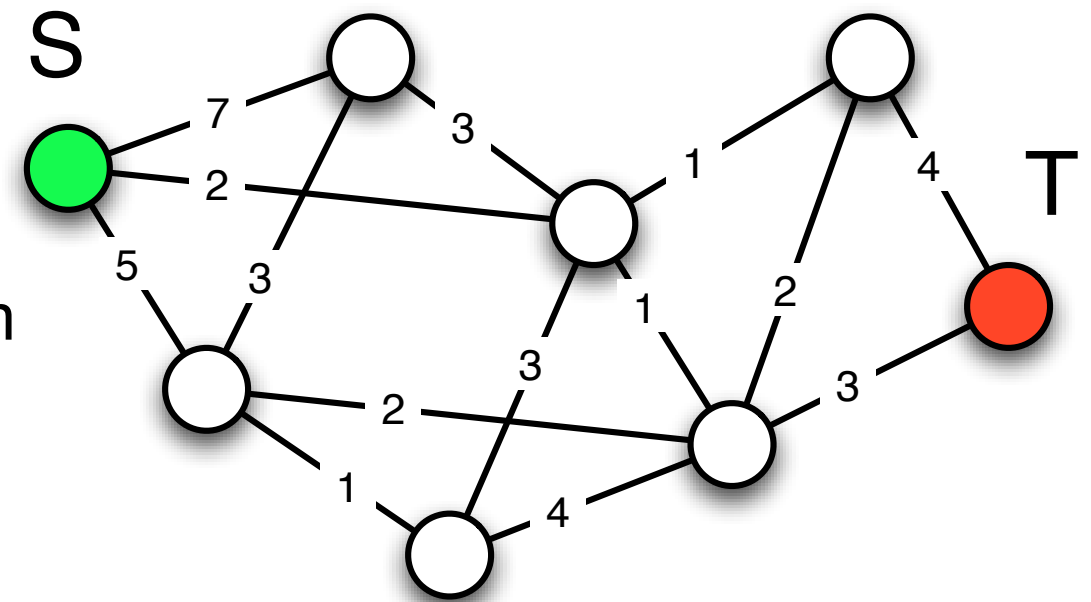
- Find a maximum flow from S to T

■ A flow is a function $f : E \rightarrow \mathbb{R}_0^+$ such that

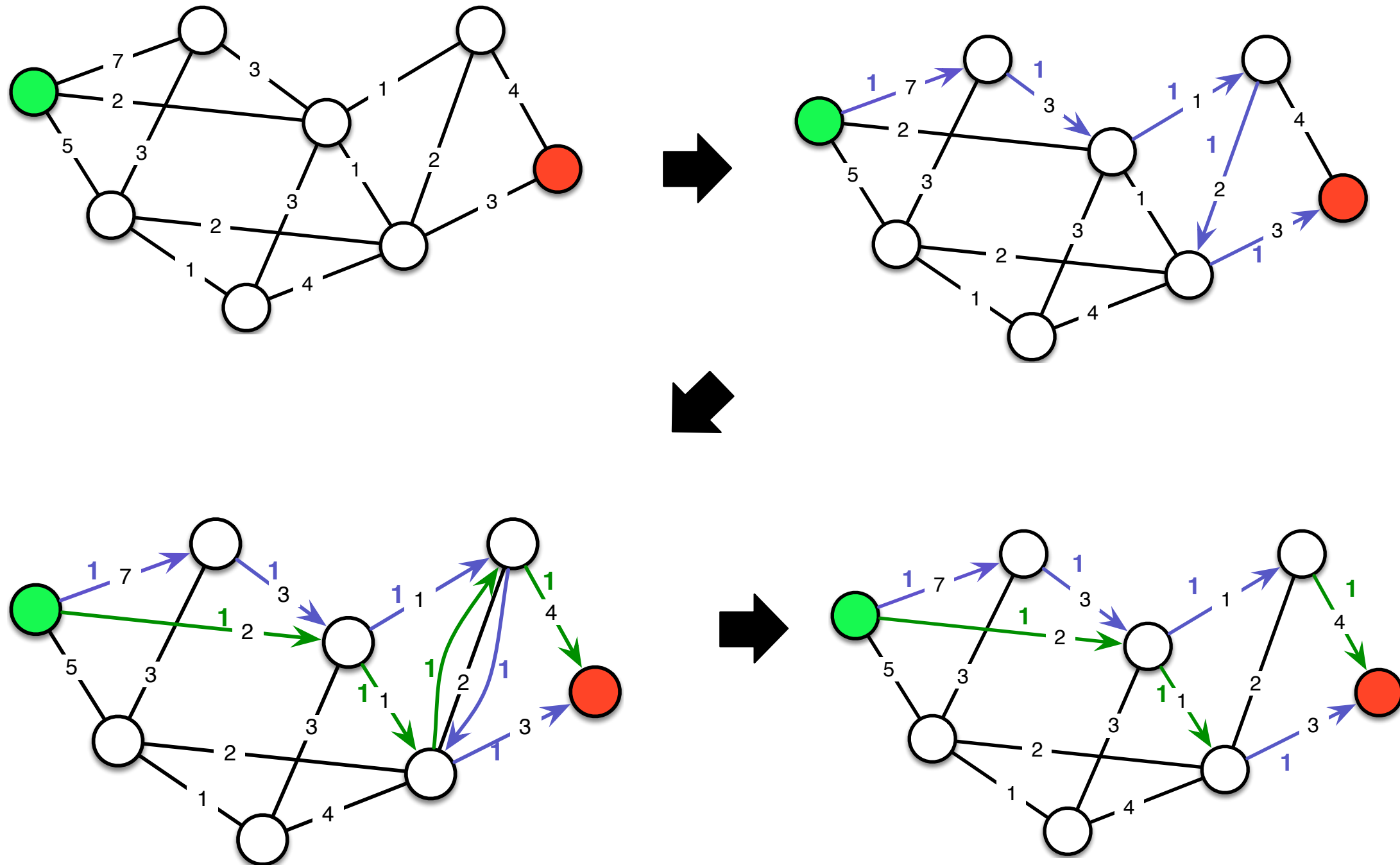
- for all $e \in E$: $f(e) \leq w(e)$
- for all $e \notin E$: $f(e) = 0$
- for all $u, v \in V$: $f(u, v) \geq 0$

■ Maximize flow

$$\sum_{u \in S} \sum_{v \in V} f(u, v)$$

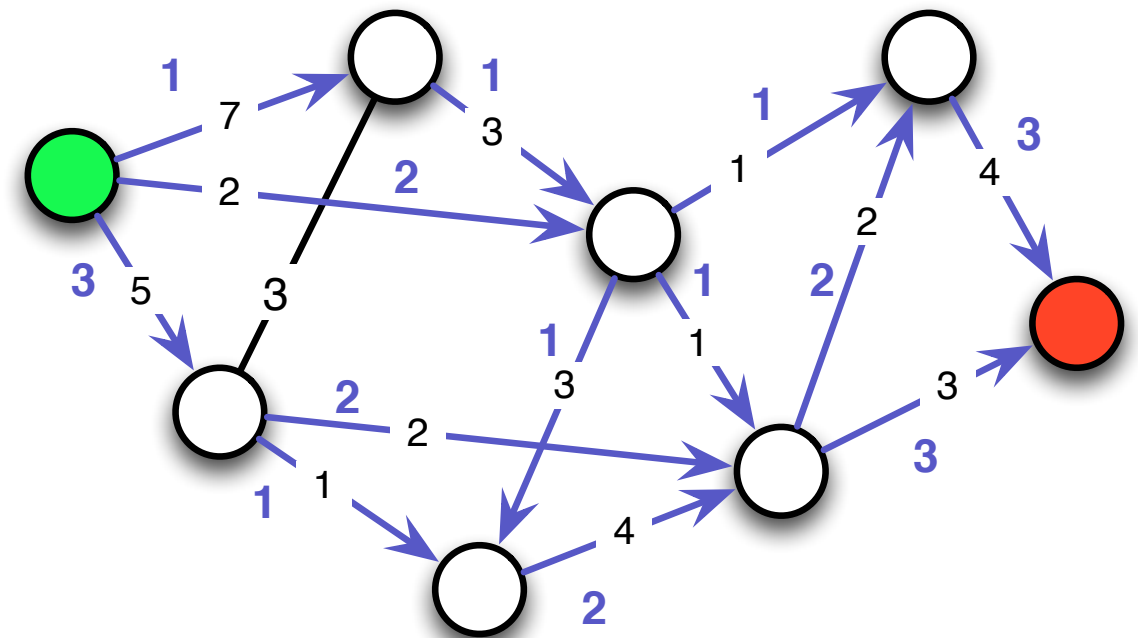


$$\forall u \in V \setminus (S \cup T) \quad \sum_{v \in V} f(v, u) = \sum_{v \in V} f(u, v)$$



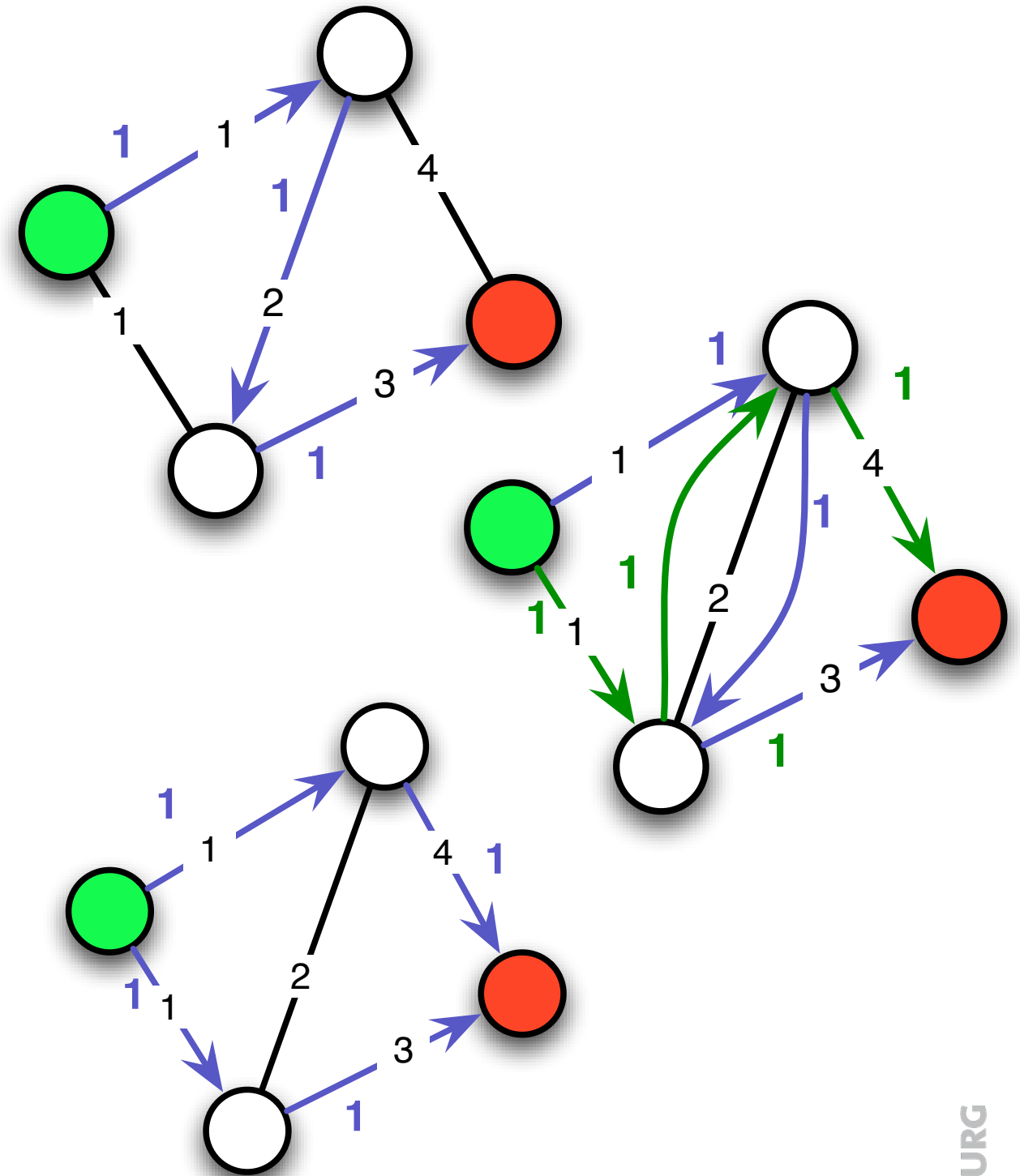
Computation of the Maximum Flow

- Every natural pipe system solves the maximum flow problem
- Algorithms
 - Linear Programming
 - for real numbers
 - the flow is described by equations of a linear optimization problem
 - Simplex algorithm (or Ellipsoid method) can solve any linear equation system
 - Ford-Fulkerson
 - also for integers
 - as long as open paths exist, increase the flow on these paths
 - open path: path which increases the flow
 - Edmonds-Karp
 - special case of Ford-Fulkerson
 - use BFS (breadth first search) to find open paths



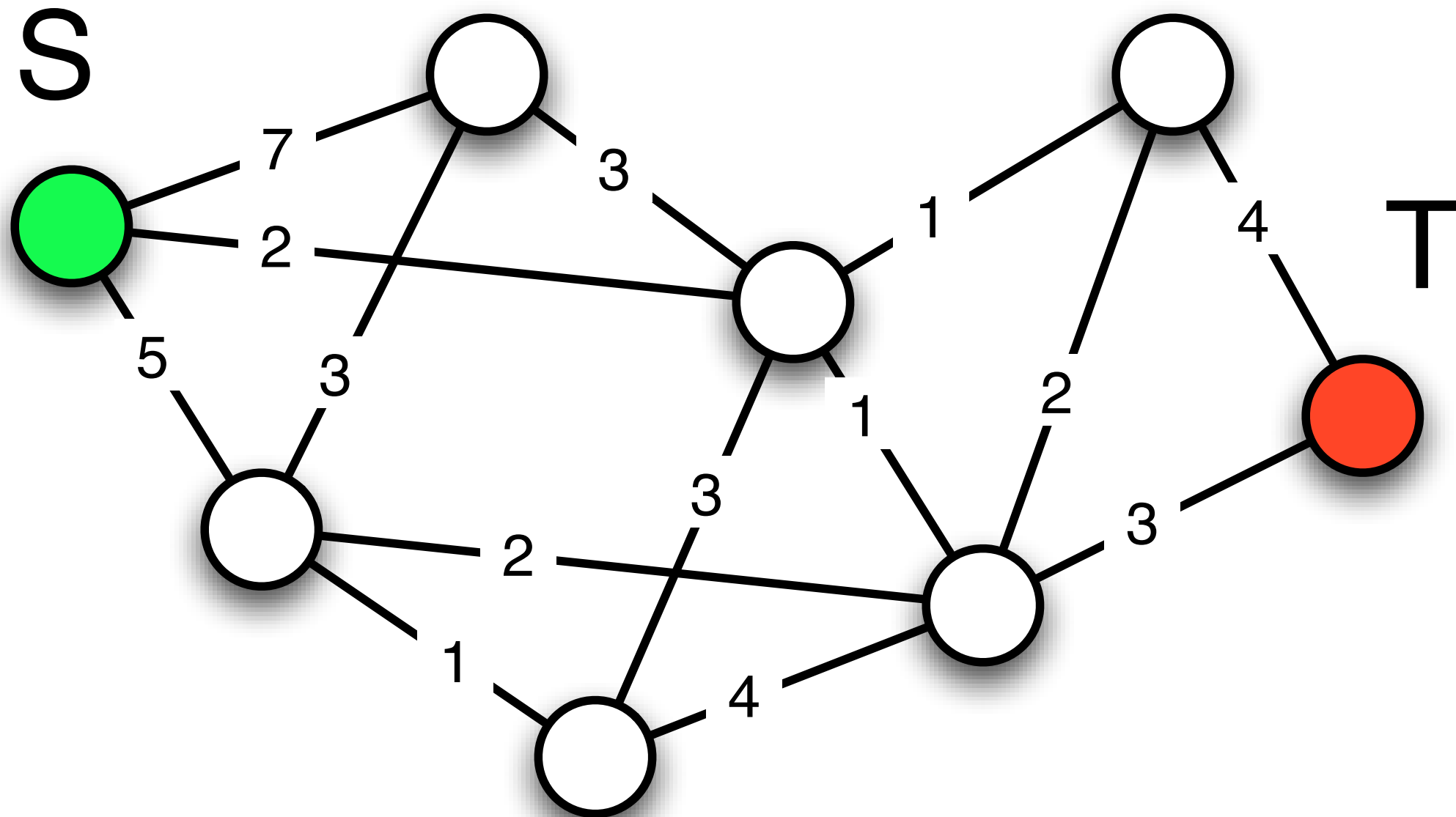
Ford-Fulkerson

- Find a path from the source node to the target node
 - where the capacity is not fully utilized
 - or which reduces the existing flow
- Compute the maximum flow on this augmenting path
 - by the minimum of the flow that can be added on all paths
- Add the flow on the path to the existing flow
- Repeat this step until no flow can be added anymore

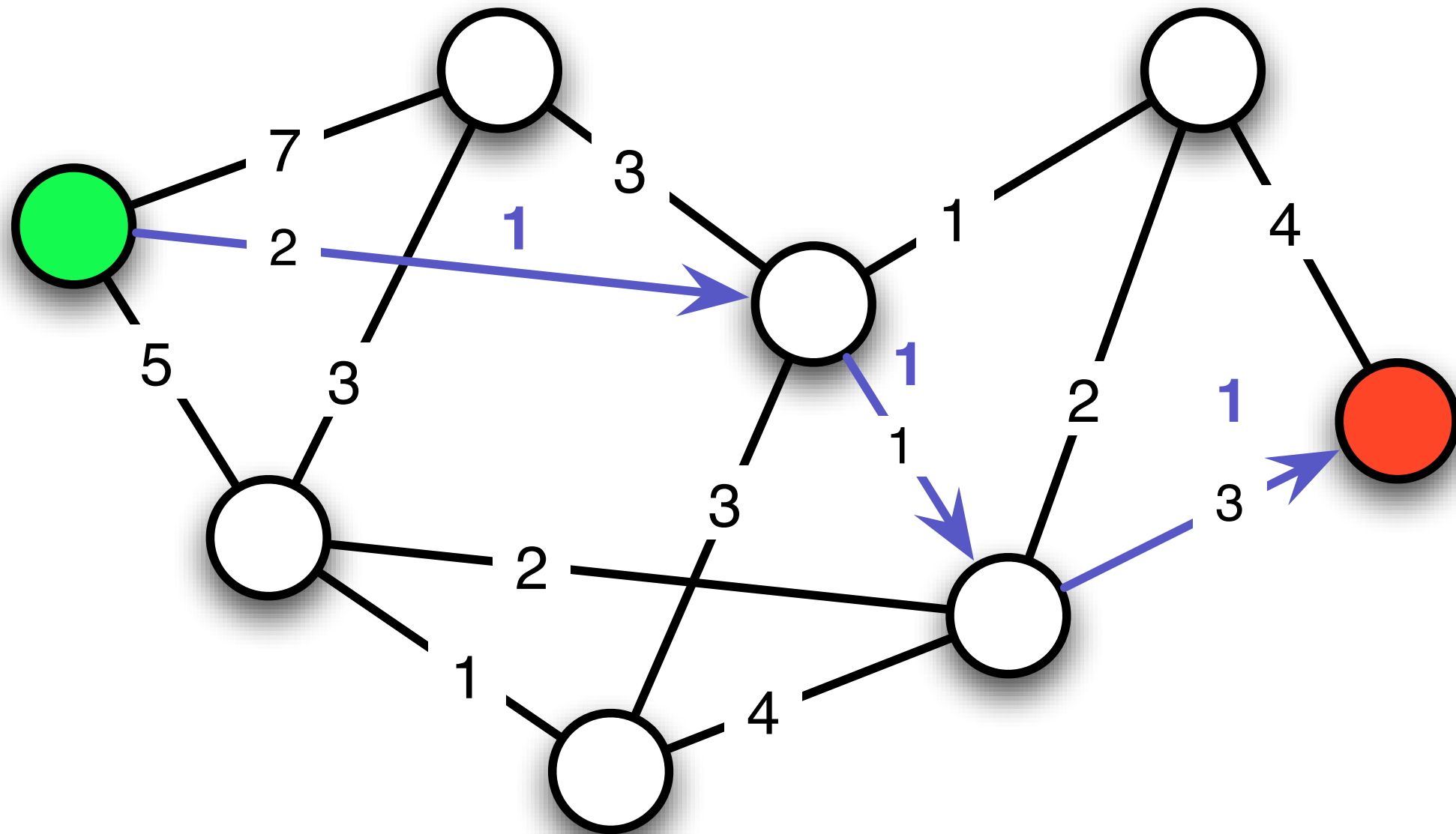


- **Search path for Ford-Fulkerson algorithm**
- **Choose the shortest augmenting path**
 - Computation by breadth-first-search
- **leads to run-time $O(|V| |E|^2)$**
 - whereas Ford-Fulkerson could have exponential run-time

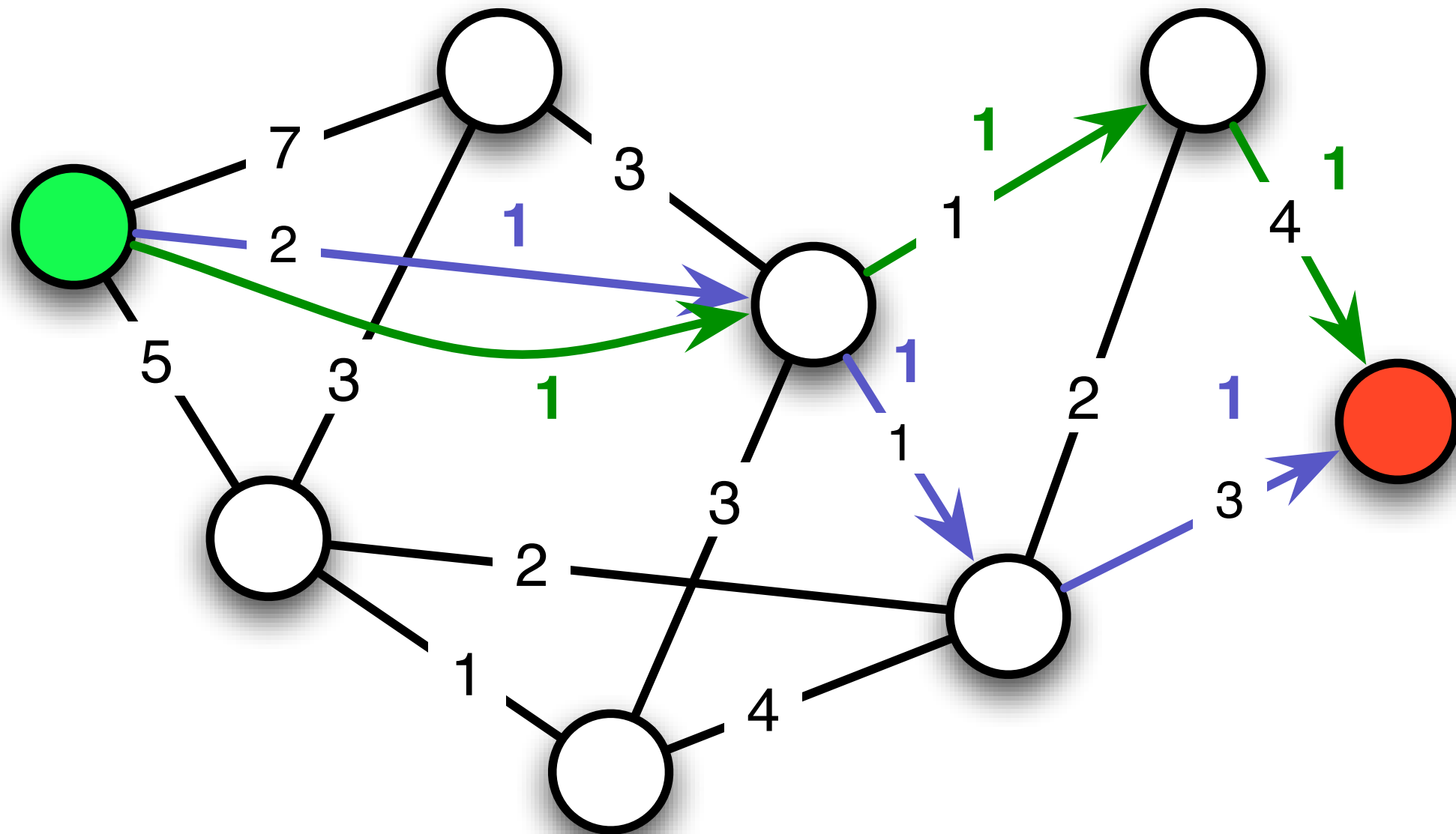
Example



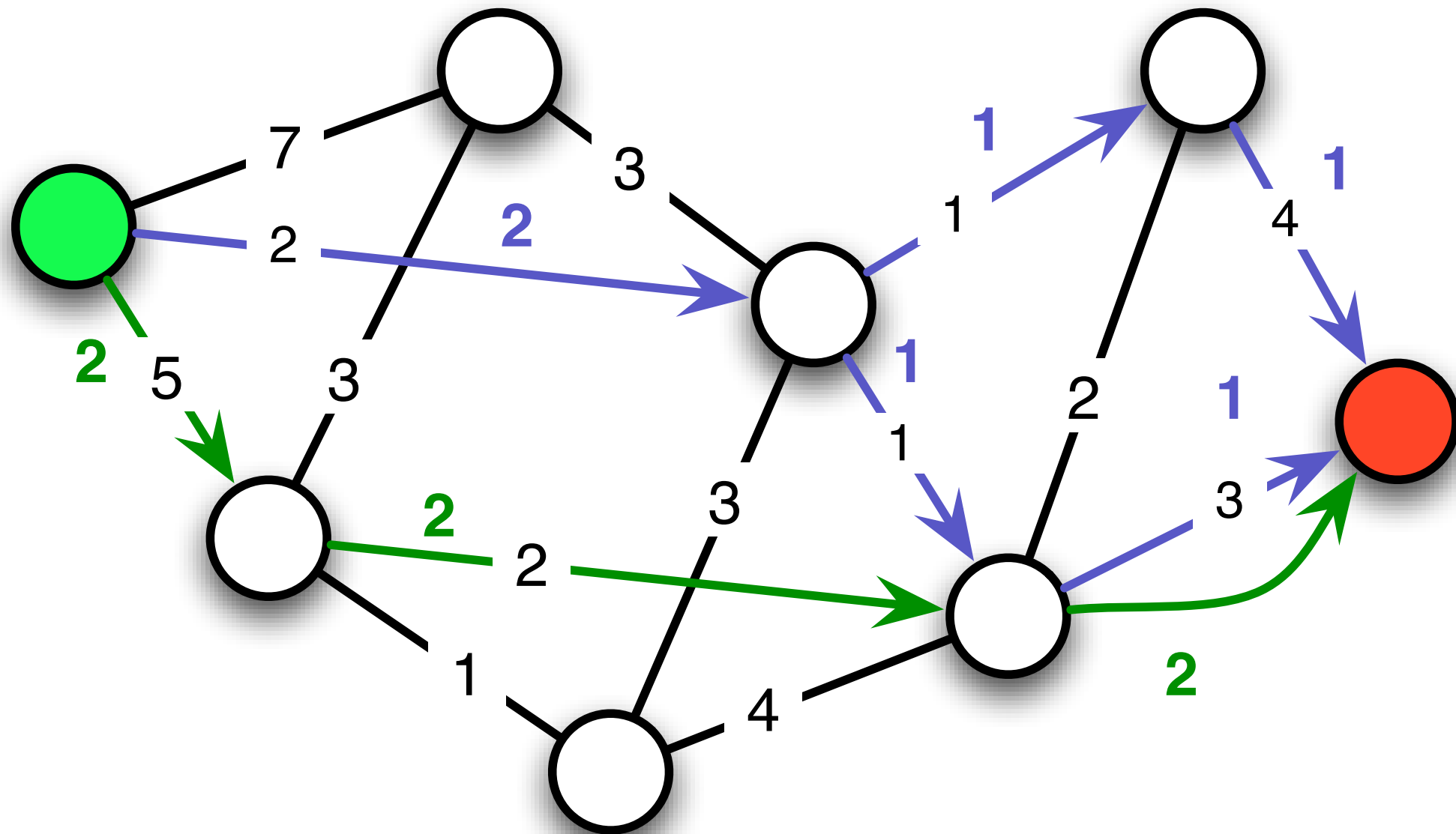
Example



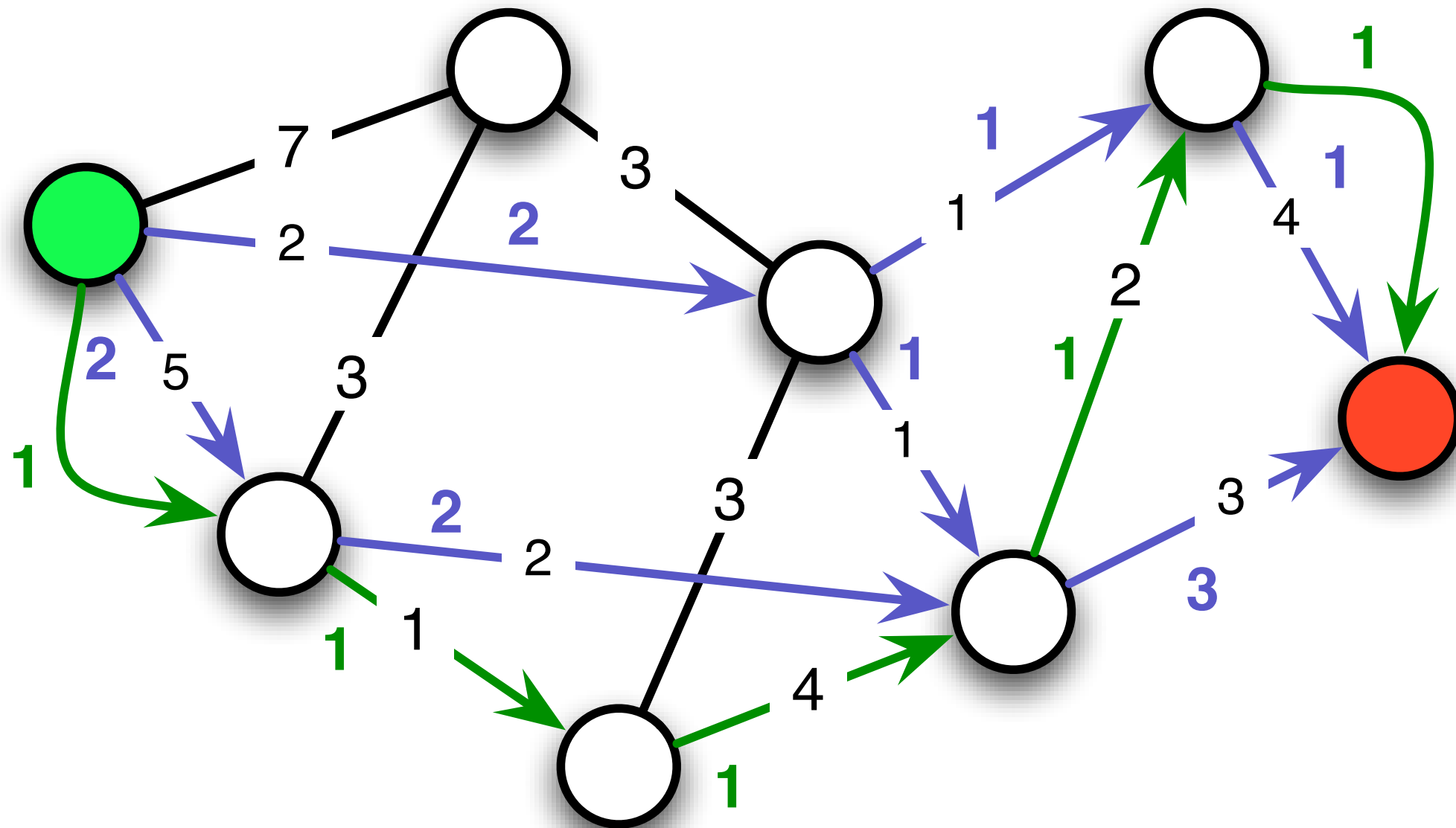
Example



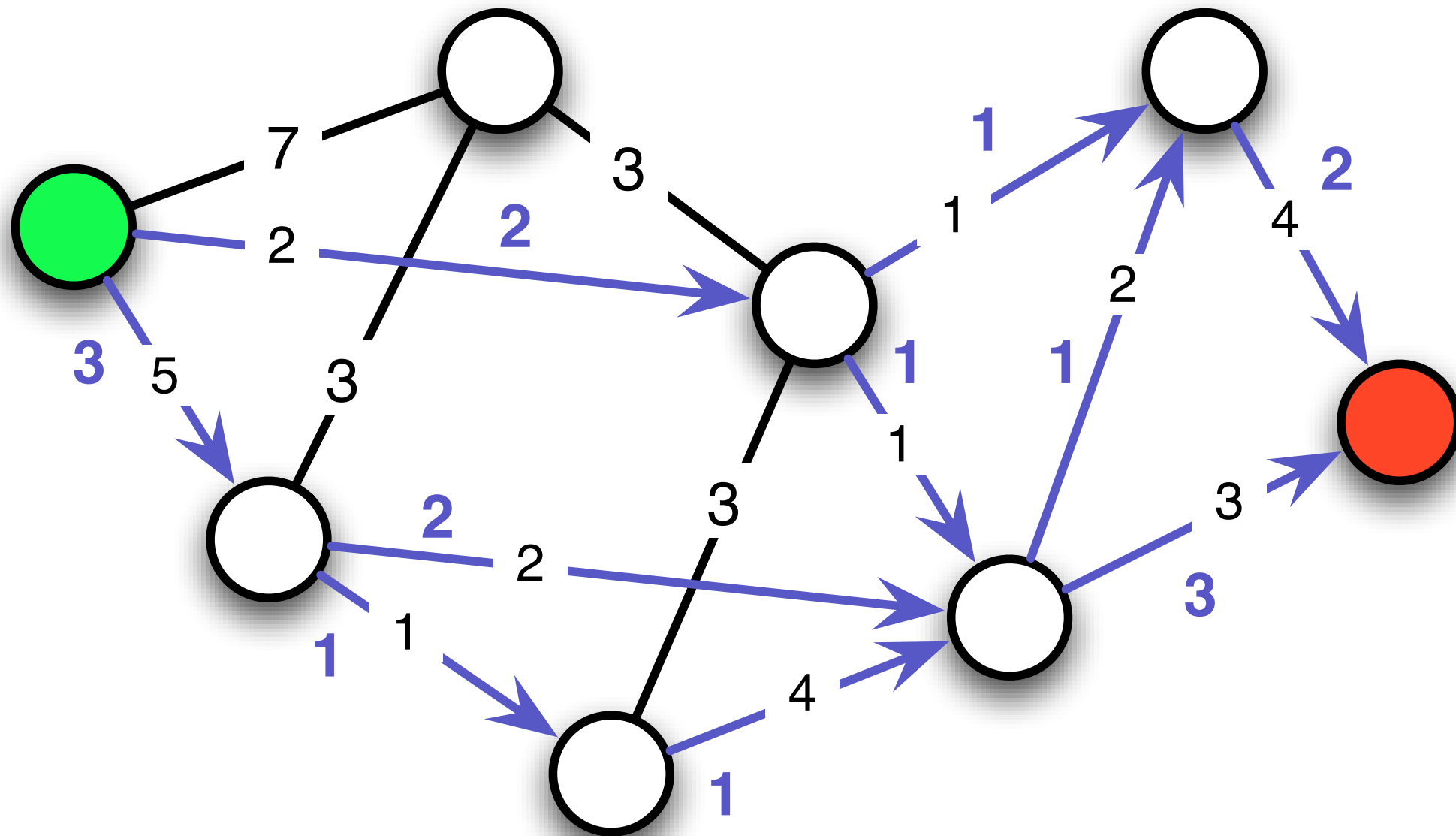
Example



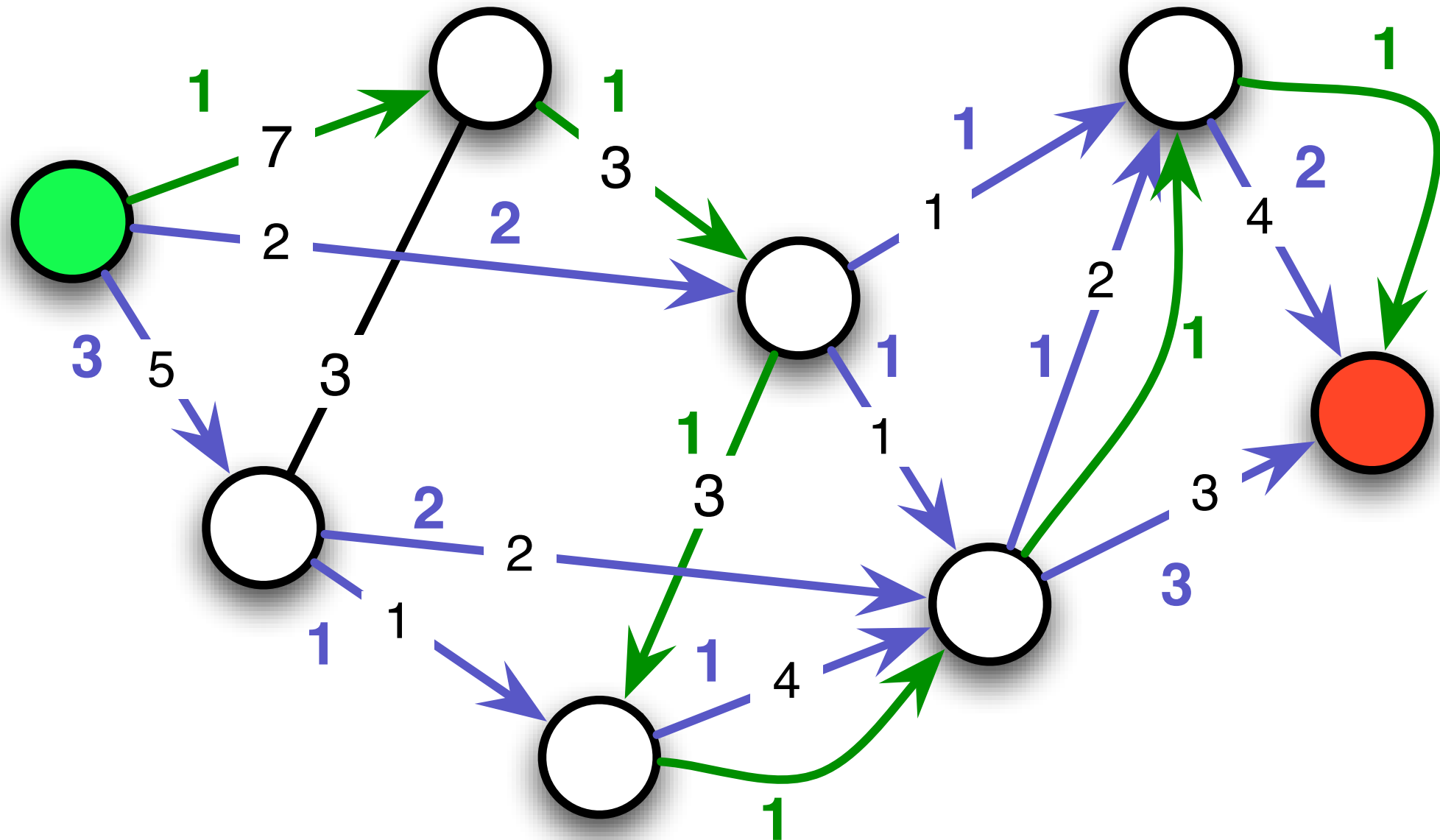
Example



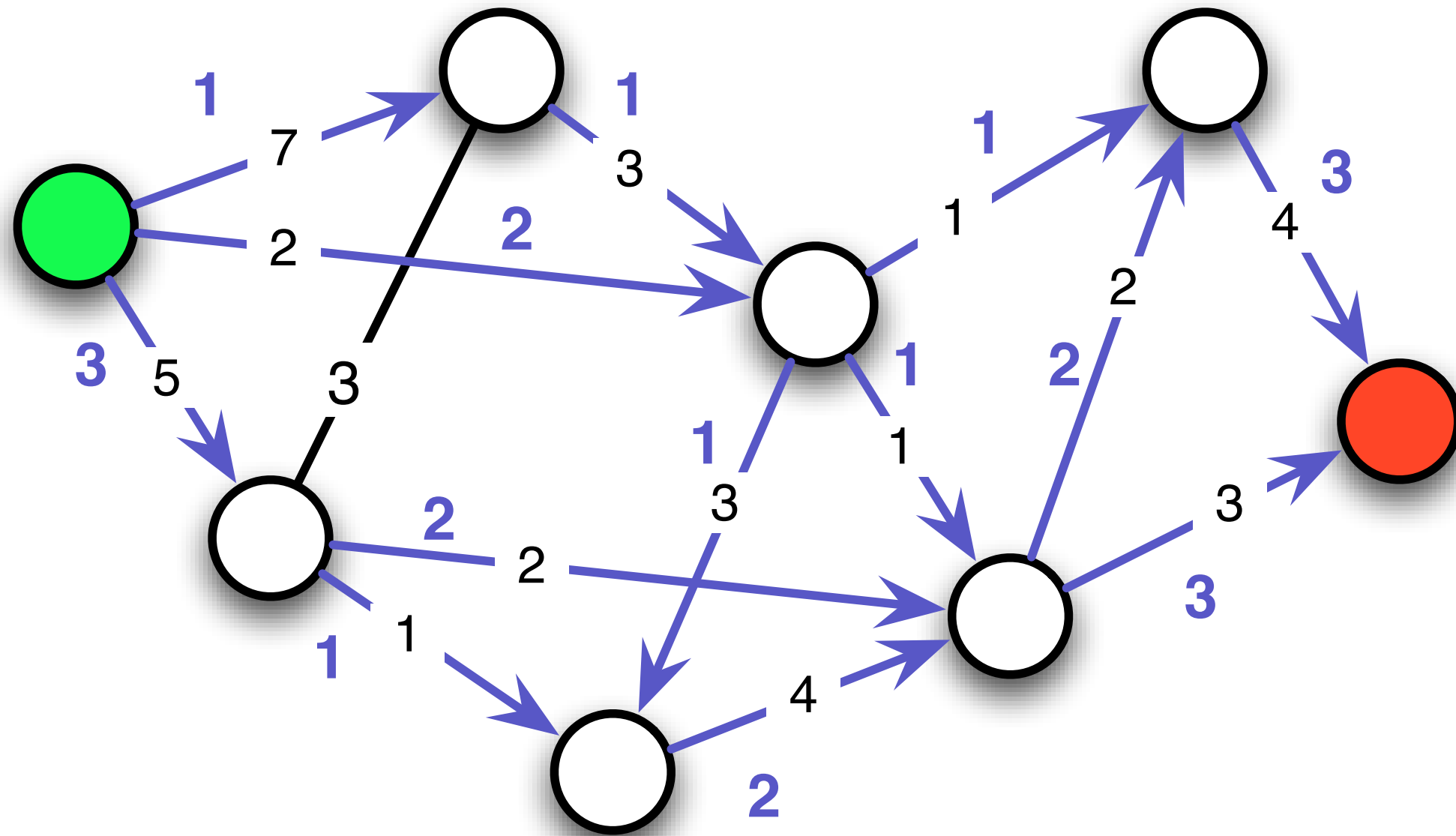
Example



Example



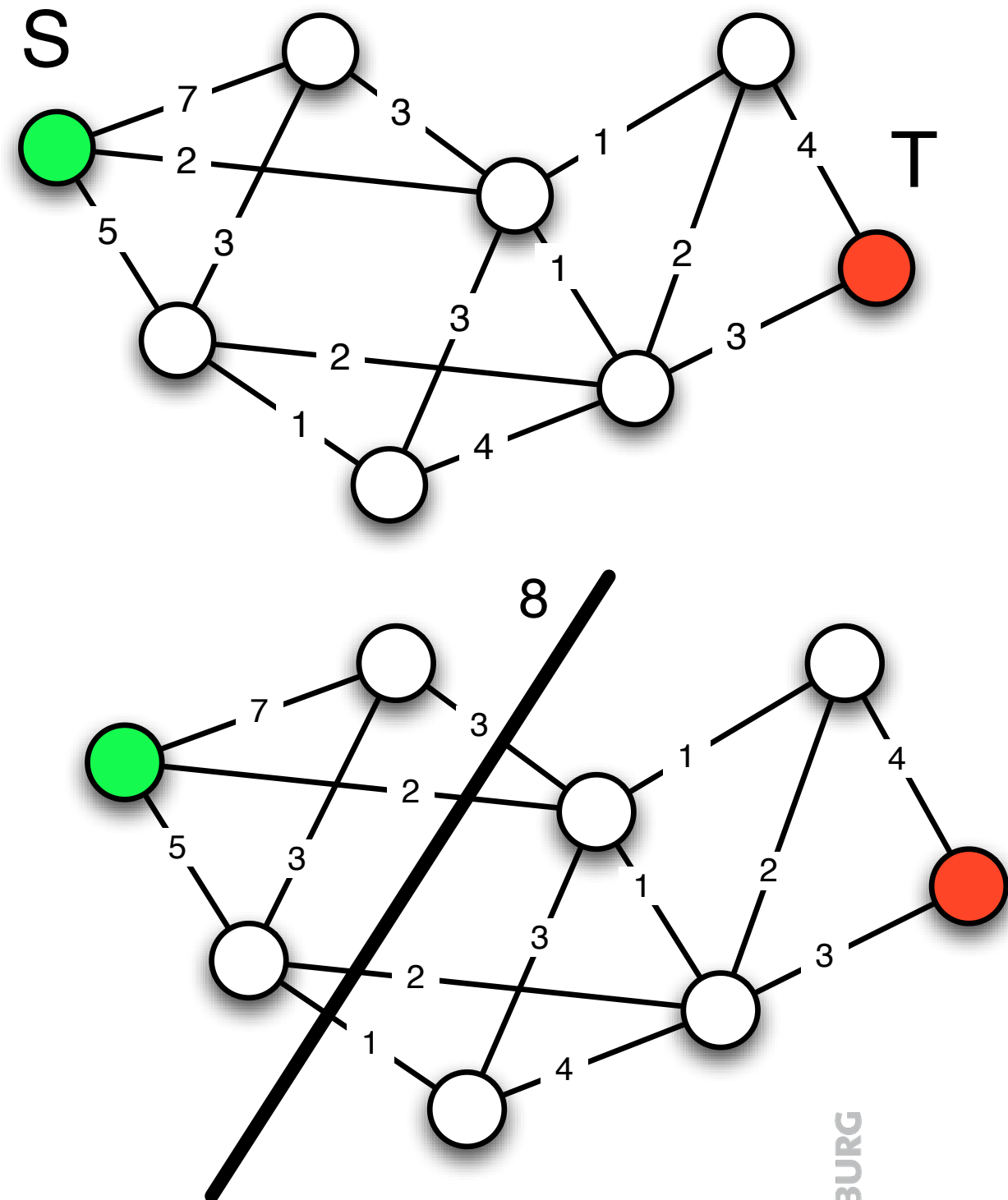
Example



Minimum Cut in Networks

- Motivation
 - Find bottleneck in networks
- Definition
 - Min Cut problem
 - Given
 - graph $G=(V,E)$
 - capacity function $w: E \rightarrow \mathbb{R}^+$,
 - sources S and targets T
 - Find minimum cut between S and T
- A cut C is a set of edges
 - such that every path from a node of S to a node of T , contains an edge of C
- The size of a cut is

$$\sum_{e \in C} w(e)$$



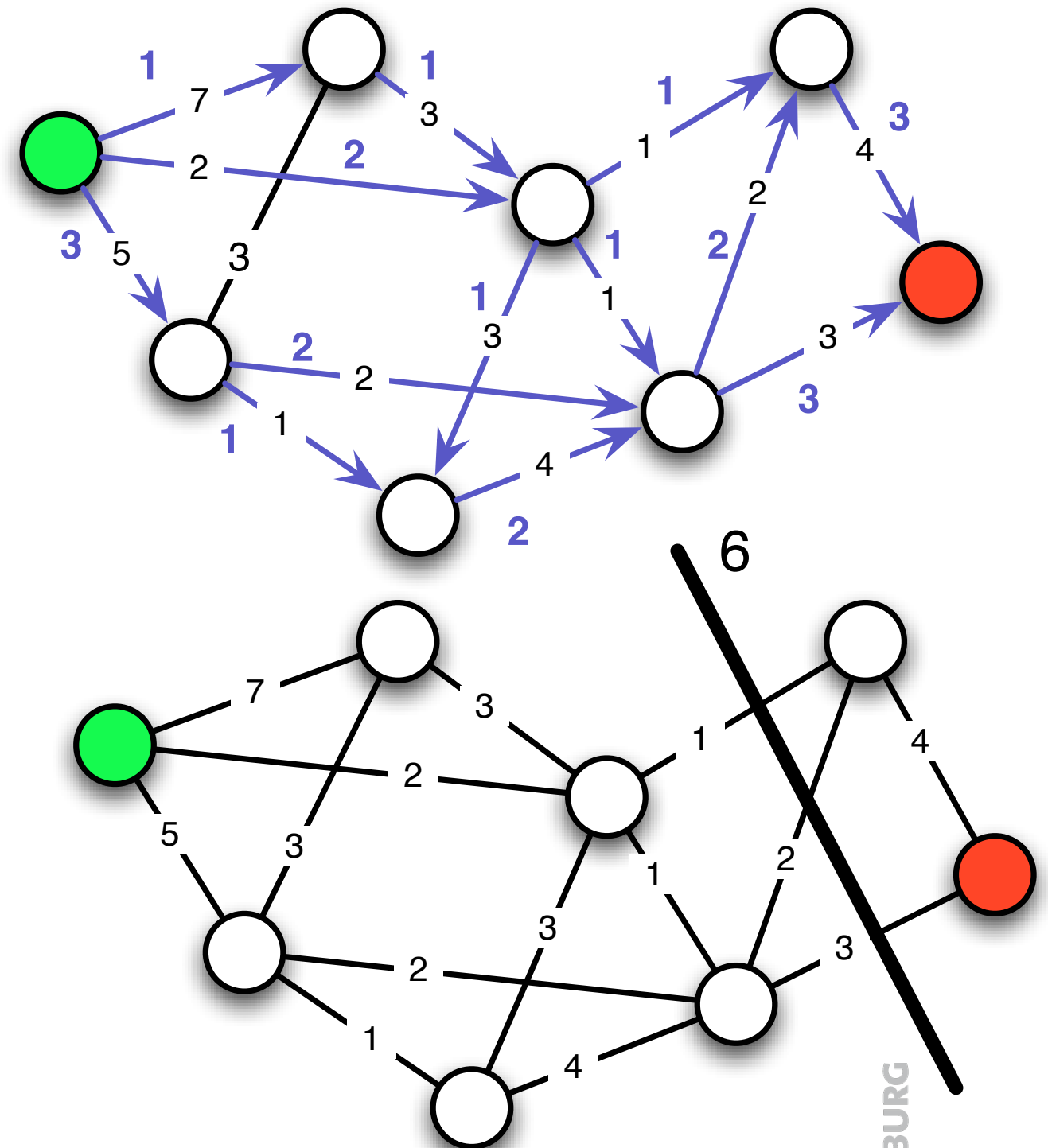
Min-Cut-Max-Flow Theorem

■ Theorem

- The minimum cut equals the maximum flow

■ Algorithms for minimum cut

- can be obtained from the maximum flow algorithms



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