



Eon: A Language and Runtime System for Perpetual Systems

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Seminar:
Ad-Hoc Networks

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Overview

- Introduction
 - Design concepts
- The Language
 - Basics
 - Syntax
 - Runtime / Compiler
- Evaluation
 - Deployment
 - Usability / Performance study

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Motivation

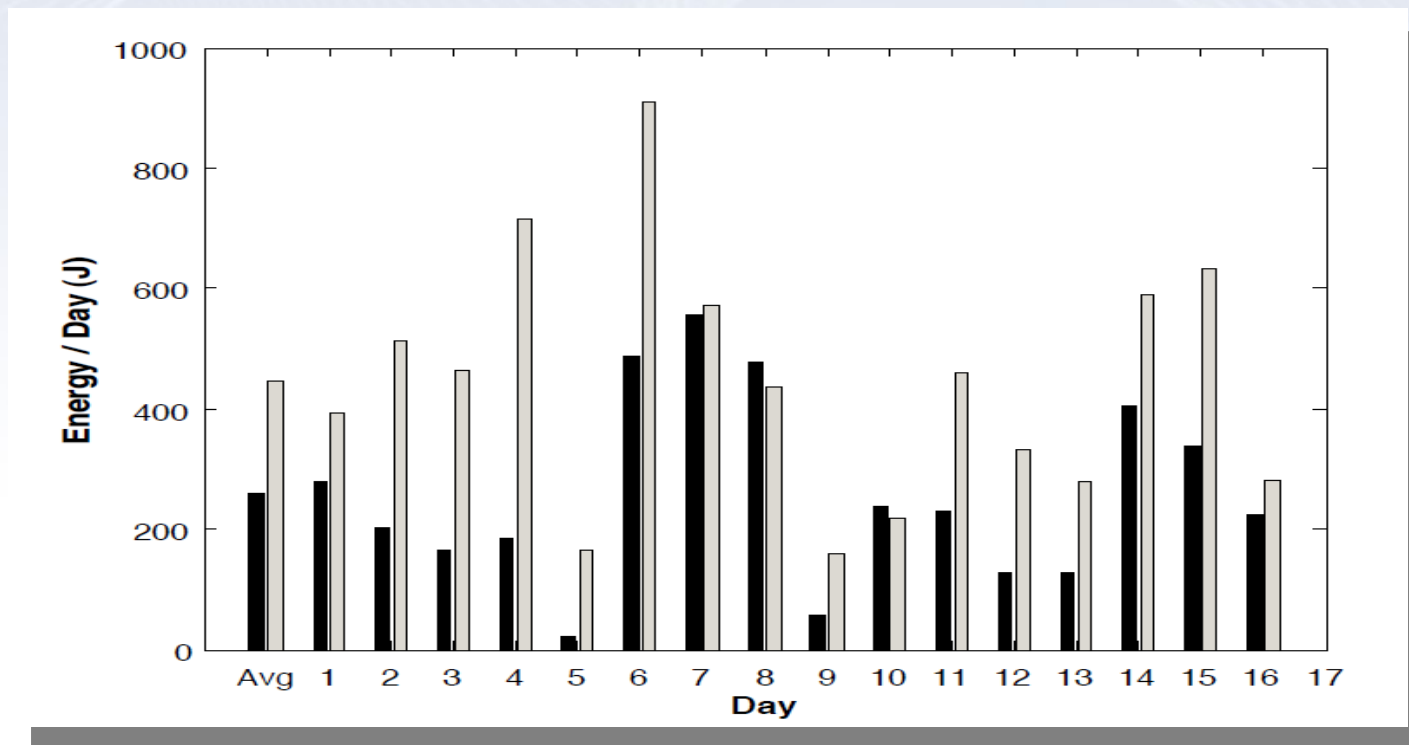
- Sensors everywhere
- Sensors with long lifetime needed
 - For long term experiments
 - Less maintainance
 - ...
- Solution:
 - Larger battery ??
 - Energy efficient programming for perpetual systems

Motivation (2)

- Perpetual system
 - Harvests energy from environment
 - Tries to survive without deadtimes
- Adaptive system
 - Dynamic energy availability
 - Varying energy costs
 - Heterogeneous hardware platforms

Motivation (3)

- Basically 2 problems for the system
 - Predicting weather (runtime)
 - Reacting appropriately (program)



Design concepts

- Energy aware programming language
 - Dynamic reactions
- Abstract energy states
 - Abstraction from hardware
- Meta language
 - Reuse of existing code
- Controll language
- Ease of use more important than complexity

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Basic idea

- Control language
- Flows
 - Sequence of actions
 - In response to external events (timers)
 - Belong to certain energy state
 - Have a defined input and output
- Separate logic and energy adaption

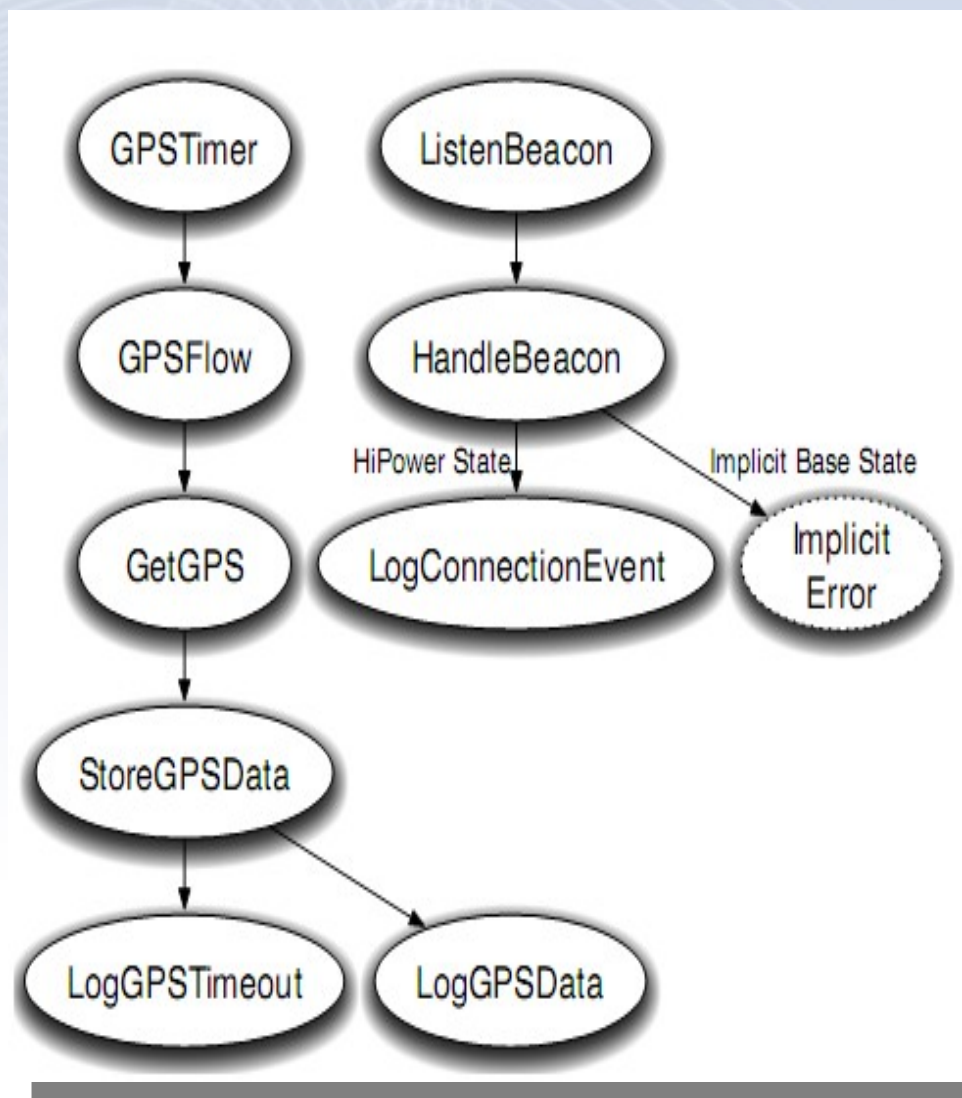
Example

- Turtle tracking application
 - Track GPS movement of endangered species



Graph representation

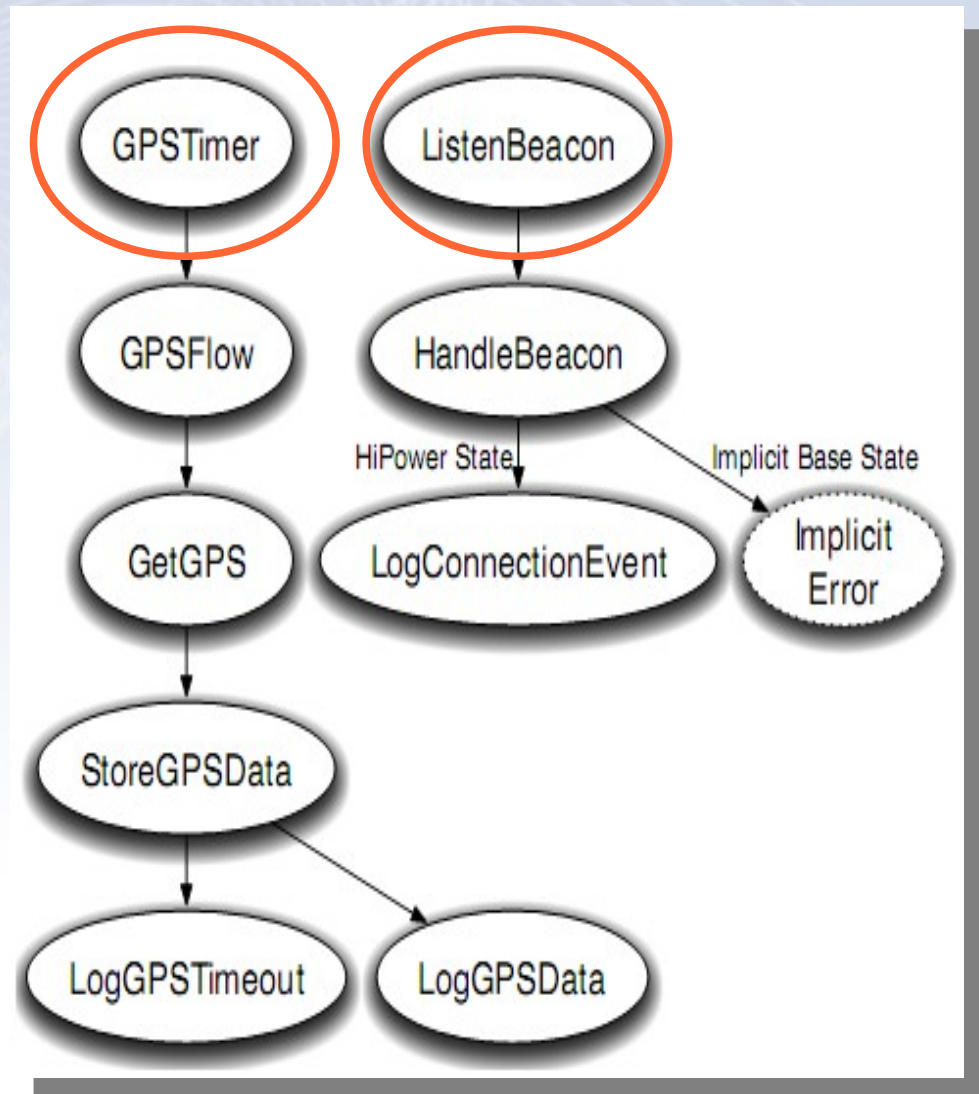
- Abstraction as dataflow graph
 - Source Nodes
 - Concrete Nodes
 - Abstract Nodes
 - Conditional Flows



Graph representation – source node

- Abstraction as dataflow graph
- **Source Nodes**
 - Feed data into other nodes

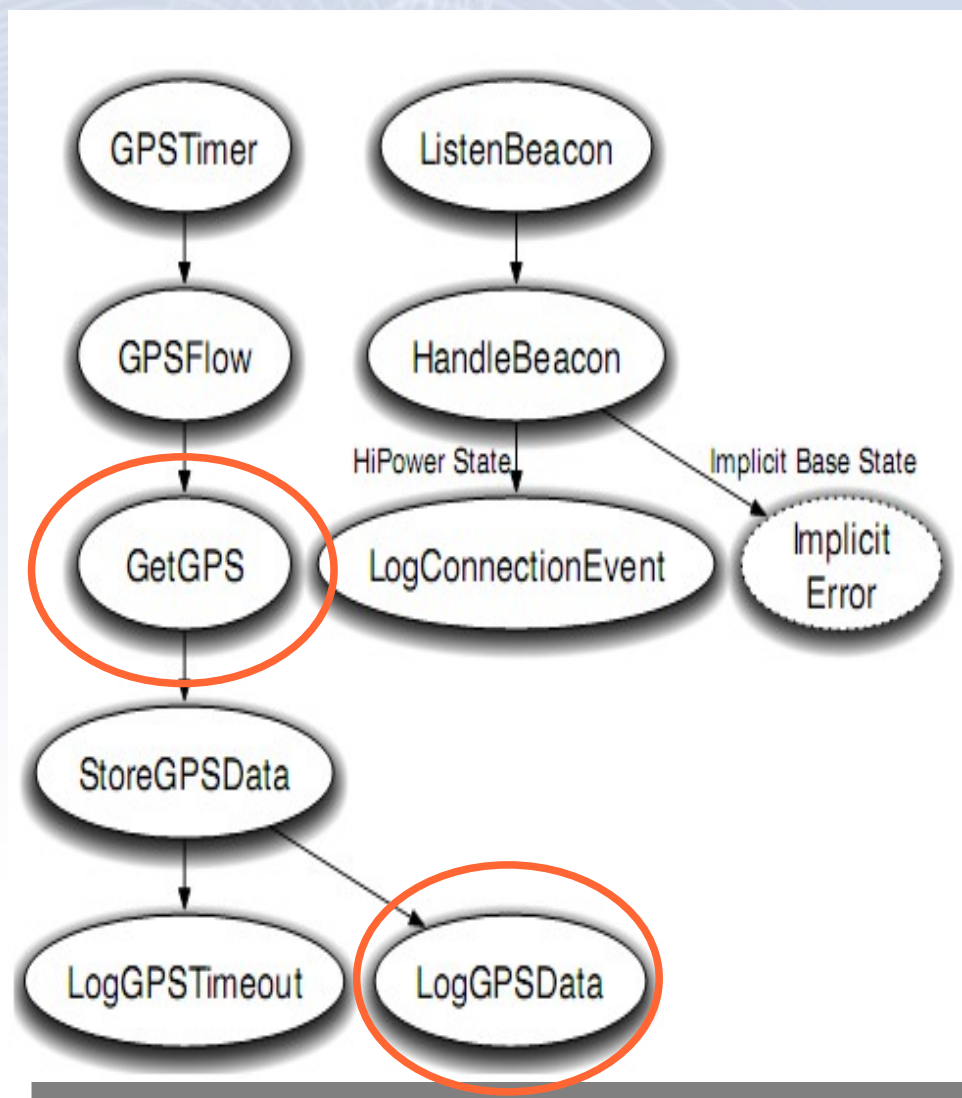
```
// Source Node Declaration  
// SYNTAX: NODENAME () => (OUTPUTS);  
ListenBeacon() => (msg_t msg);  
GPSTimer() => ();
```



Graph rep. – concrete node

- Abstraction as dataflow graph
- **Concrete Node**
 - Node that links to C/nesC code

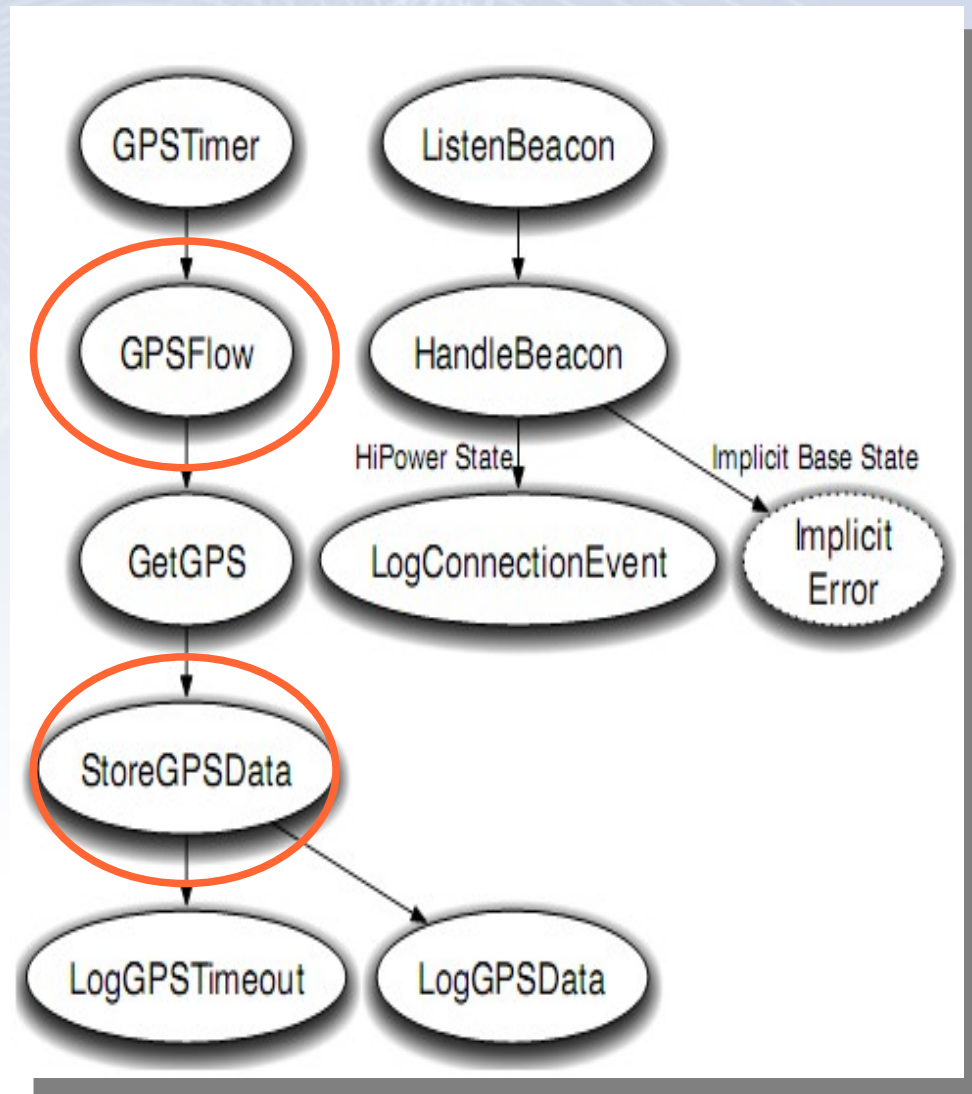
```
// Concrete Node Declaration
// SYNTAX: NODENAME (INPUTS) => (OUTPUTS);
GetGPS() =>
    (GpsData_t data, bool valid);
LogGPSData(GpsData_t data bool valid)
    => ();
```



Graph rep. – abstract node

- Abstraction as dataflow graph
- **Abstract Node**
 - Dataflow through concrete / abstract nodes

```
// Abstract Nodes and Predicate Flows
// SYNTAX: ABSTRACT[[type,..][state]] =
// CONCRETE->...CONCRETE;
GPSFlow = GetGPS -> StoreGPSData;
StoreGPSData:[*,gotfix][*] = LogGPSData;
StoreGPSData:[*,*][*] = LogGPSTimeout;
```

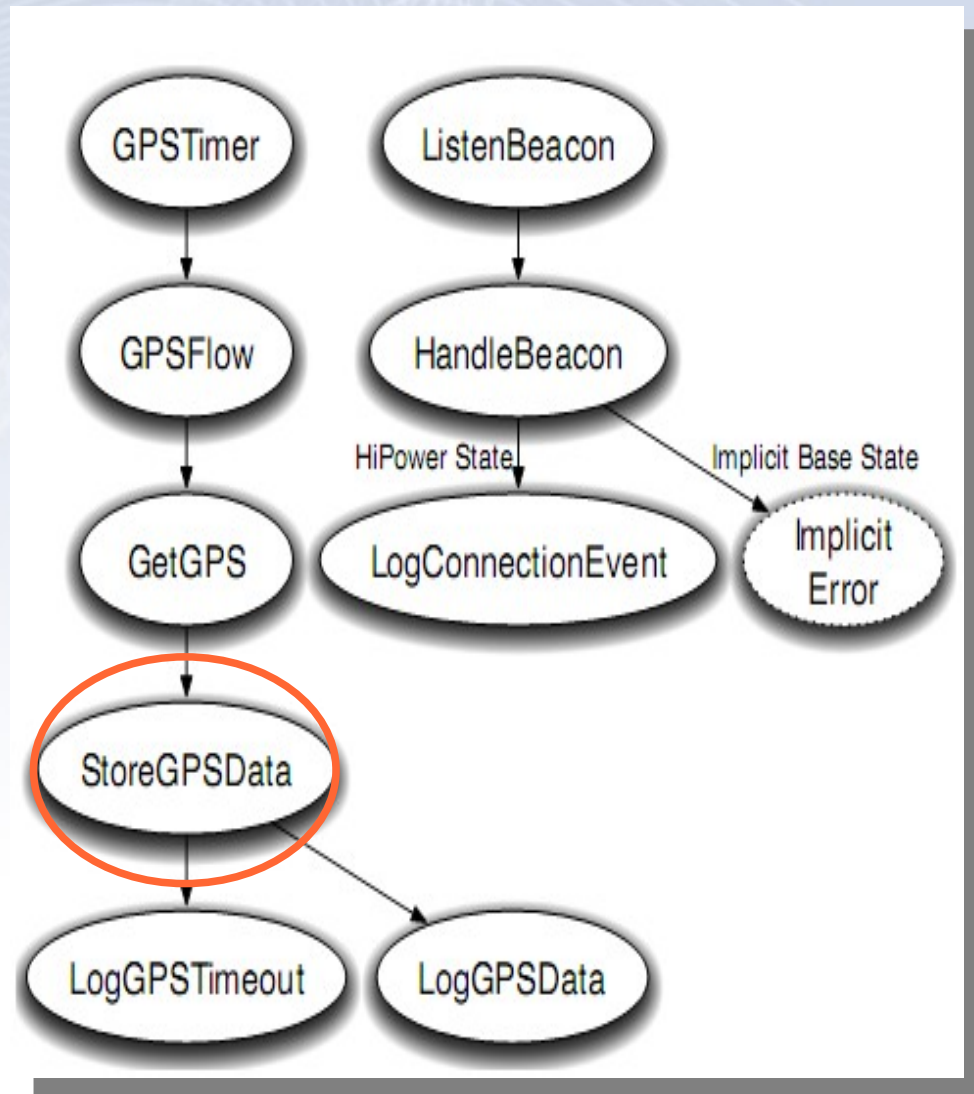


Graph rep. – conditional flow

- Abstraction as dataflow graph
- **Conditional Flow**
 - Use of predicate types

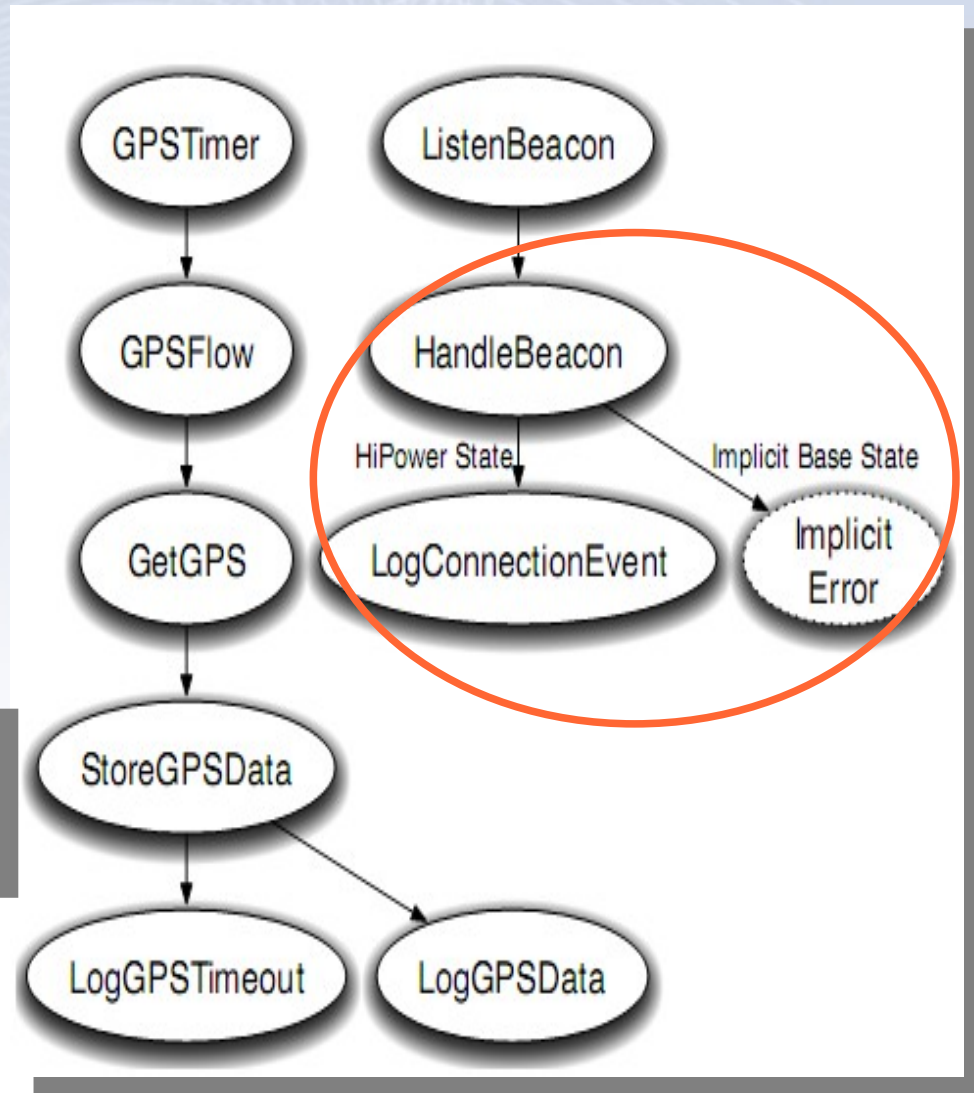
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StoreGPSData:[*,gotfix][*] = LogGPSData;
StoreGPSData:[*,*][*] = LogGPSTimeout;
```

```
// Predicate Types
// SYNTAX: typedef PRED_TYPE PRED_TEST
typedef gotfix TestGotFix;
```



Graph rep. – conditional flow (2)

- Abstraction as dataflow graph
- **Conditional Flow**
 - Can be used in conjunction with energy levels



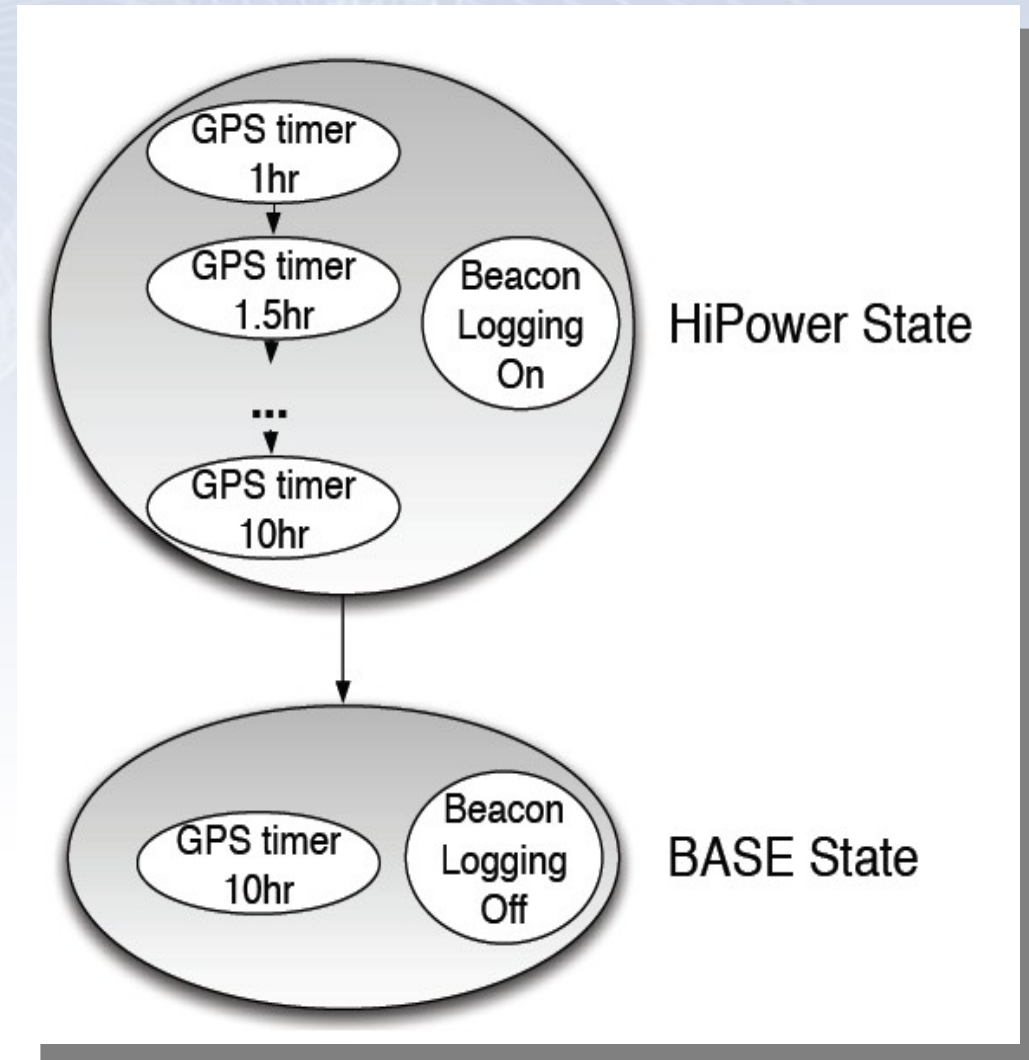
```
// Abstract Node using Energy Predicates  
HandleBeacon:[*,*][HiPower]  
= LogConnectionEvent;
```


Power levels

- Discreet levels representing battery state
 - No utilities
- Implicit BASE state
- Higher ordered states are more desirable
 - And more energy intensive
- Used in
 - Conditional flows
 - State based parameters

Power levels (2)

- Timer intervals can be adjusted
 - Handled by the Runtime
- Features can be disabled
 - Hardware
 - Software
 - Data quality
 - Energy state based paths



Criticism ?

- No fine grain adjustments
 - Only timer frequency
 - State ordering instead of utilities
 - Discreet states
 - Adjustment of data quality can only be done in discreet steps
- Code has to be wrapped or structured differently

Runtime

- Goals
 - Broad array of low-power hardware
 - Online measurements
 - No training
 - Low overhead
- Ensure that the right paths are chosen
 - Predict state
 - Own consumption
 - Weather forecast

Energy adaption algorithm

- Highest fidelity while avoiding two states
 - Full battery
 - Higher level of fidelity could be provided
 - Energy is wasted
 - Empty battery
 - Sudden deadtimes could occur
 - Execution of high priority flows is prevented
- Anything in between is equivalent good

Energy adaption algorithm (2)

- Performs a search on possible states
 - Initial: Highest state with lowest timer-freq.
 - Lower state until stable (on short interval T_i)
 - Future prediction: $2^n \cdot T_i$ $n = \{1 \dots N\}$
 - Binary search on timers

Energy attribution

- Measure consumption for the path
 - Hardware support
- Downside, Eon requires
 - Fuel gauge
 - Fine-grained current measurement
- Energy consumption can be allocated
 - Energy production/loss

Energy source model

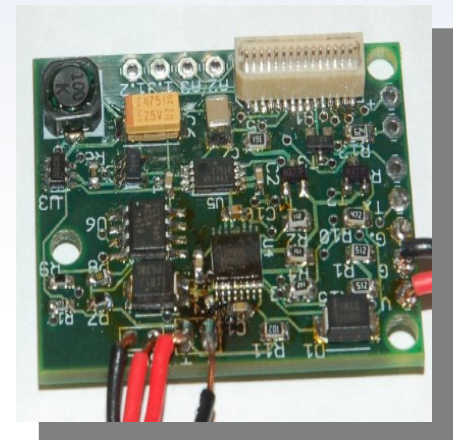
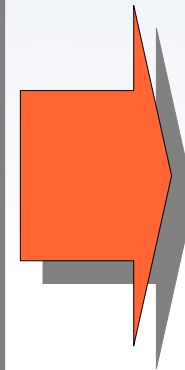
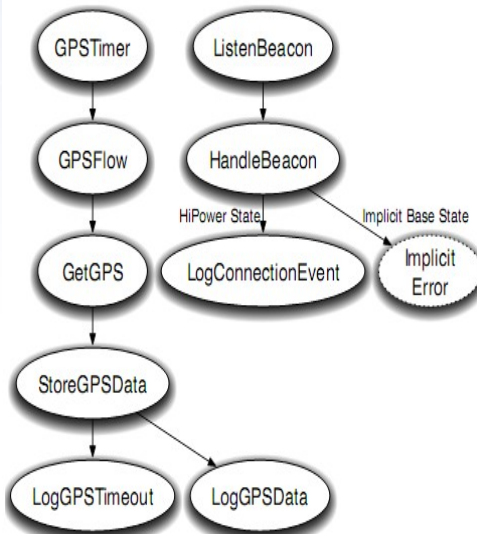
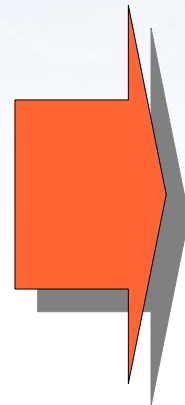
- Energy production in following days == energy production in recent days

$$E(t+1) = \alpha E(t) + (1 - \alpha) E(t-1)$$

Compiler

- Compilation in 3 steps
 - Nodes are built
 - Edges are attributed
 - User supplied code is linked

```
1 // Predicate Types
2 // SYNTAX: typedef PRED_TYPE PRED_TEST
3 typedef gotfix TestGotFix;
4
5 // Source Node Declaration
6 // SYNTAX: NODENAME () => (OUTPUTS);
7 ListenBeacon() => (msg_t msg);
8 GPSTimer() => ();
9
10 // Concrete Node Declaration
11 // SYNTAX: NODENAME (INPUTS) => (OUTPUTS);
12 GetGPS() =>
13   (GpsData_t data, bool valid);
14 LogGPSData(GpsData_t data bool valid)
15   => ();
16 LogGPSTimeout(GpsData_t data bool valid)
17   => ();
18 LogConnectionEvent(msg_t msg) => ();
19
20 // Regular Sources
21 // SYNTAX: source NODENAME => NODENAME;
22 source ListenBeacon => HandleBeacon;
23
```



Compiler - Simulation

- Trace-based
 - Feed with weather data
- Test different adaption policies without deployment
- Profile energy behavior
 - Locate bottlenecks

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Deployment

- Deployment driven approach on developing Eon
- Different environments/applications
 - Turtle tracking
 - Car tracking
 - Remote camera application

Turtle tracking

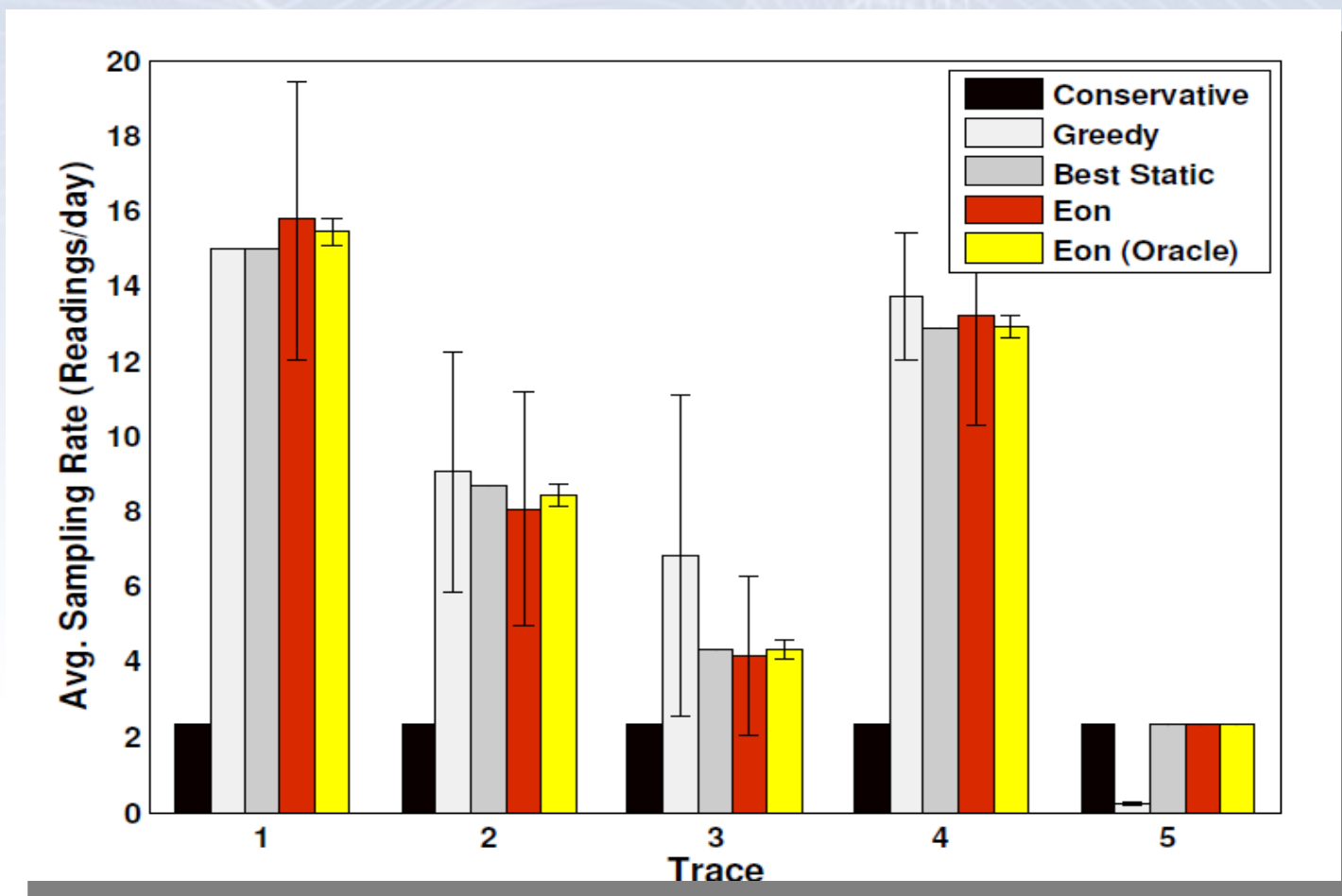
- Solar powered node fixed on turtle shell
- Report GPS data to scientists
 - Until now: had to be done manually
- Result: Failed
 - Turtles spent 98% of time underwater
 - Early hibernation
- Car tracking had to be done to get evaluation data

Adaption study

- Loop acquired data in simulator
 - 3 months of data from 2 weeks
- GPS sampling rate can be changed
 - Conservative, static
 - Greedy, static
 - Best sustainable
 - Eon (Predictor)
 - Eon (Oracle)
- 5 different devices

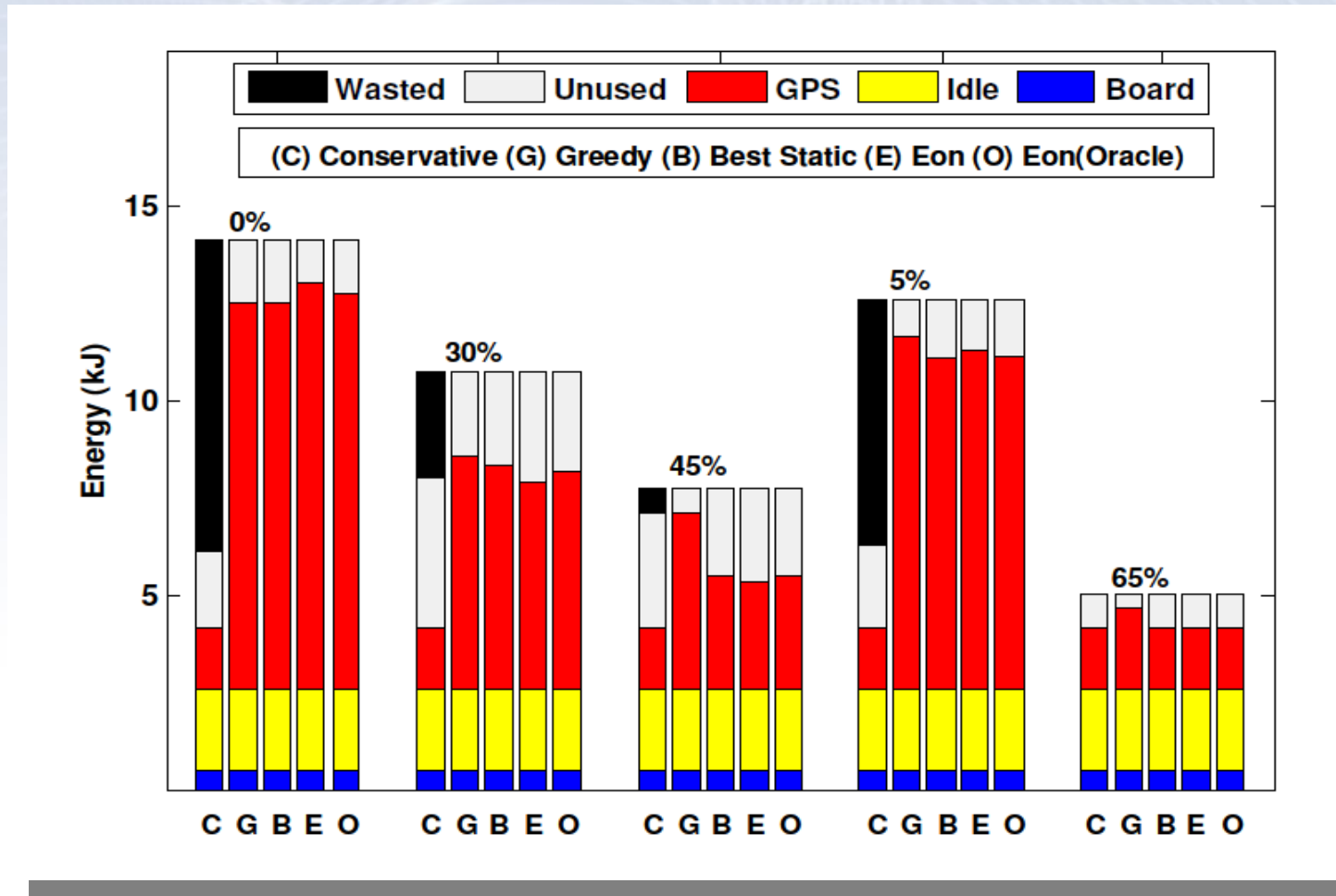
Adaption study - results

- Sampling rates of the devices



Adaption study – results (2)

- Energy consumption by board parts / strategy



Remote camera

- Image streaming
 - High power state
- Image storage
 - Low power
- Building whole application in < 3 hours

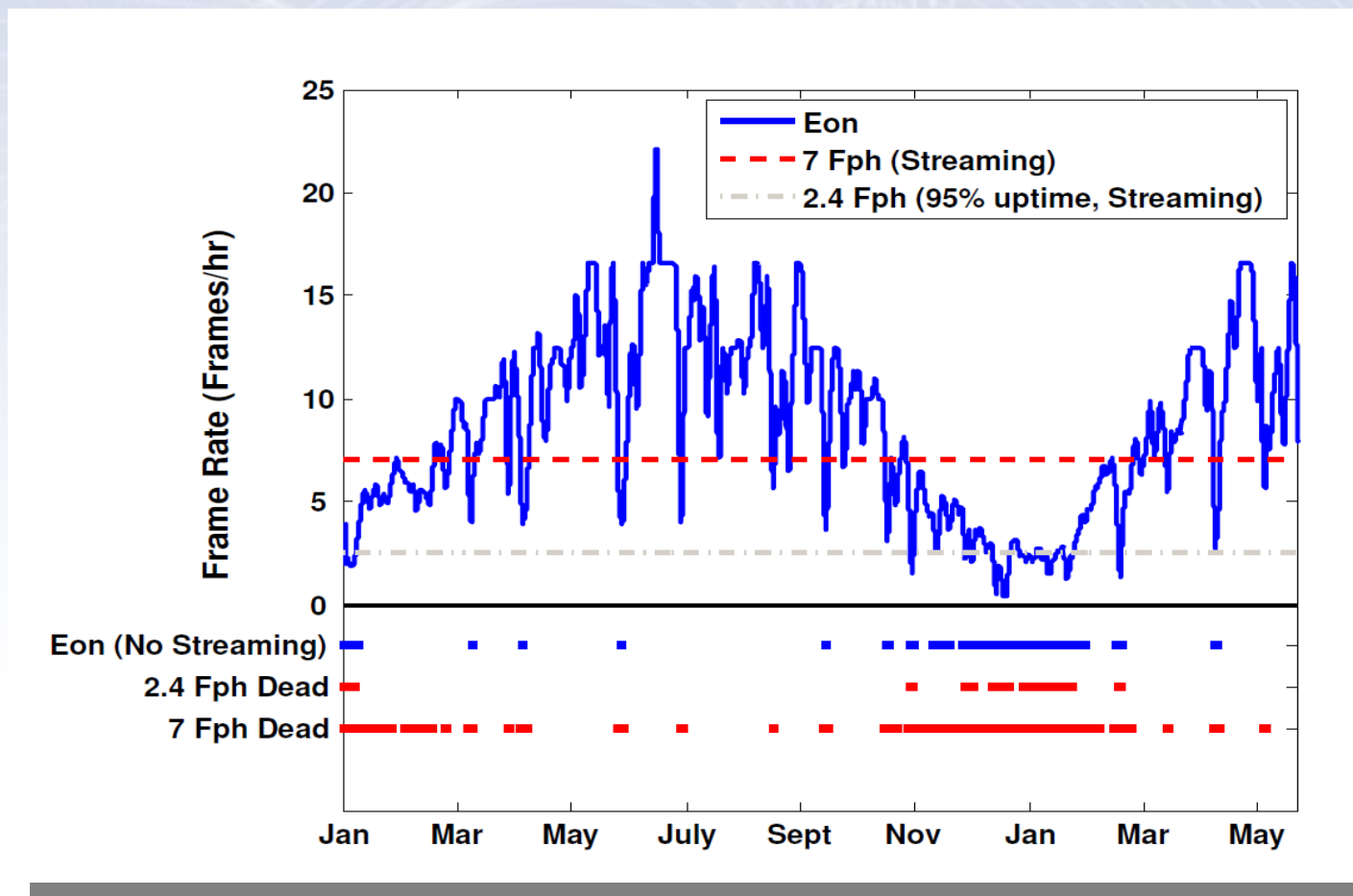


Energy consumption

- Collect solar traces
 - Map solar intensity to power output of cells
 - Use climate tables to produce long term data
- Policies
 - 2.4 Fph, static
 - 7 Fph, static
 - Eon (stream / query)

Energy consumption - results

- Graph including deadtimes / query mode

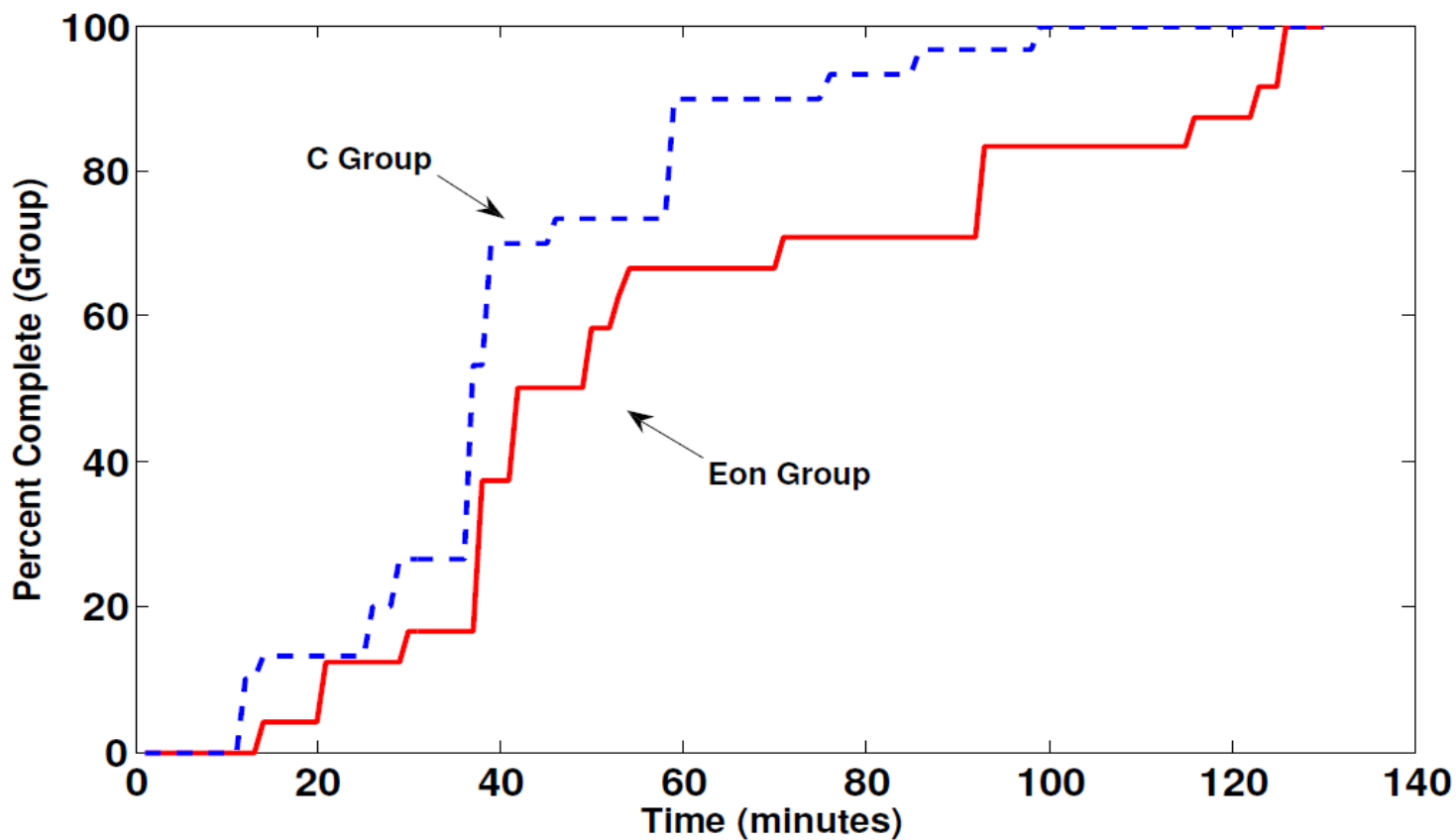


User study

- Programming sensor applications
 - Setup
 - Group of experienced C programmers
 - Provided with the same solar energy predictor Eon uses
 - Group of first time Eon users
- 1st Application samples data and saves it
- 2nd Get the most samples without running out of battery

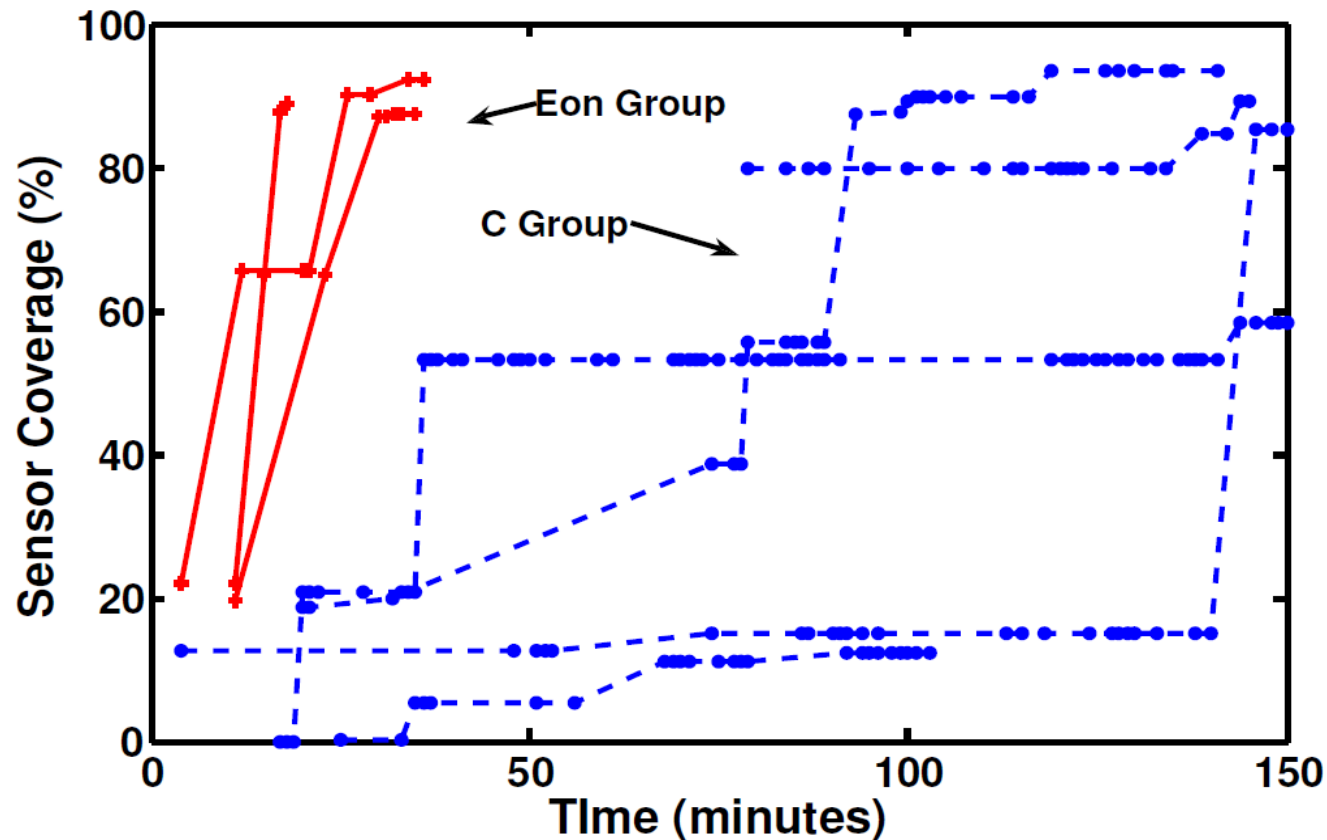
User study - results

- Task 1 has been finished



User study – results (2)

- Task 2 has been finished



Conclusion

- Benefits
 - Ease of use
 - Only approach that targets energy adaption at programming level
 - Proven efficiency
- Downsides
 - Existent code has to be rewritten

Fin

Thank you for your attention !