Chapter 12: Modeling and Analysis of Distributed Applications

Petri-Nets

- Petri-nets are abstract formal models capturing the flow of information and objects in a way which makes it possible to describe distributed systems and processes at different levels of abstraction in a unified language.
- Petri-nets have the name from their inventor Carl Adam Petri, who introduced this formalism in his PhD-thesis 1962.

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¹ van der Aalst: The Application of Petri nets to Workflow Management. Journal of Circuits, Systems, and Computers 8(1): 21:66 (1998)





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Complaints processing: keeping things together



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Petri-nets

Petri-nets model system dynamics.

- Activities trigger state transitions,
- activities impose control structures,
- applicable for modelling discrete systems.

- Uniform language,
- open for formal analysis, verification and simulation,
- graphical intuitive representation.

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Section 12.1 Elementary System Nets

Basic elements of an elementary System Net (eS-Net)

- System states are represented by *places*, graphically circles or ovals.
- A place may be marked by an arbitrary number of *tokens* graphically represented by black dots.
- System dynamics is represented by *transitions*, graphically rectangles.
- Transitions represent activities (events) and the causalities between such activities (events) are represented by edges.
- Multiplicities represent the consumption, respectively creation of resources which are caused by the occurence of activities.

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3-Philosopher-Problem

 b_j : philosopher starts eating; e_j : philosopher stops eating; i_j : philosopher is eating; g_j : fork on the desk; $1 \le j \le 3$.



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A transition *may* occur when certain conditions with respect to the markings of its directly connected places are fulfilled; the *occurence* of a transition - also called its *firing* - effects the markings of its directly connected edges, i.e. has local effects.

The *surrounding* of a transition *t* is given by *t* and all its directly connected places:



 s_1, \ldots, s_k are called *preconditions* (*pre-places*), s_{k+1}, \ldots, s_n *postconditions* (*post-places*).

A place which is pre- and post-place at the same time is called a loop.

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A *net* is given as a tripel N = (P, T, F), where

- P, the set of *places*, and T, the set of *transitionen*, are non-empty disjoint sets,
- $F \subseteq (P \times T) \cup (T \times P)$, is the set of directed edges, called *flow relation*, which is a binary relation such that $dom(F) \cup cod(F) = P \cup T$.

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Let N = (P, T, F) be a net and x \in P \cup T.

xF := \{y \mid (x, y) \in F\}

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For $p \in P$, pF is the set of *post-transitions* of p; Fp is the set of *pre-transitions* of p. For $t \in T$, tF is the set of *post-places* of t; Ft is the set of *pre-places* of t.

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A mapping $P \rightarrow NAT \cup \{\omega\}$ is called ω -marking. ω represents an infinitly large number of tokens.

Arithmetic of ω :

 $\omega - n = \omega, \omega + n = \omega, n \cdot \omega = \omega, 0 \cdot \omega = 0, \omega > n$

where $n \in NAT$, n > 0.

A *marking* represents a possible system state.

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A marking represents a possible system state.

A *eS-Net* is given as $N = (P, T, F, V, m_0)$, where

- (*P*, *T*, *F*) a net,
- $V: F \rightarrow NAT^+$ a multiplicity,
- m₀ a marking called initial marking.

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A transition may fire once it is enabled.

Let $N = (P, T, F, V, m_0)$ a eS-Net, *m* a marking and $t \in T$ a transition.

• t is enabled at m, if for all pre-places $p \in Ft$ there holds:

$$m(p) \geq V(p,t).$$

Whenever t is enabled at m, then t may fire at m. Firing t at m transforms m to m', $m[t \succ m'$, in the following way:

$$m'(p) := \begin{cases} m(p) - V(p, t) + V(t, p) & \text{falls } p \in Ft, p \in tF, \\ m(p) - V(p, t) & \text{falls } p \in Ft, p \notin tF, \\ m(p) + V(t, p) & \text{falls } p \notin Ft, p \in tF, \\ m(p) & \text{sonst.} \end{cases}$$

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Let places in P be linearily ordered.

- Markings of a net can be considered as vectors of nonnegative integers of dimension | P |, called *place-vectors*.
- Transitions t can be characterized as vectors of nonnegative integers of dimension
 | P |, called transition vectors Δt, t⁺, t⁻:

Let $N = (P, T, F, V, m_0)$ a eS-Net, $p \in P$ and $t \in T$.

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Place and transition vectors at work:

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$$m \leq m'$$
, if $m(p) \leq m'(p)$ for $\forall p \in P$,

• m < m', if $m \le m'$, however $m \ne m'$.

• t is enabled at m iff $t^- \leq m$,

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We denote W(T) the set of words with finite length over T; $\epsilon \in W(T)$ is called the *empty word*.

The length of a word $w \in W(T)$ is given by I(w). We have $I(\epsilon) = 0$.

Let m, m' be markings of P and $w \in W(T)$. We define a relation $m[w \succ m']$ inductively:

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• $R_N(m) := \{m' \mid m[* \succ m'\}, \text{ the set of markings reachable from } m \text{ by } N,$

L_N(m) := {w | ∃m' : m[w≻m'}, the set of all words representing firing sequences of transitions of N starting at m,

•
$$\Delta w := \sum_{i=1}^{n} \Delta t_i$$
, wobei $w = t_1 t_2 \dots t_n$.

Results

- [$* \succ$ is reflexiv and transitiv.
- $m[w \succ m' \Rightarrow (m + m^*)[w \succ (m' + m^*), \forall m^* \in NAT^{|S|}.$ (Monotonie)

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Reachability graph

Let $N = (P, T, F, V, m_0)$ a eS-Net. The *Reachability graph* of N is a directed graph $EG(N) := (R_N(m_0), B_N); R_N(m_0)$ is the set of nodes and B_N is the set of annotated edges as follows:

$$B_N = \{(m, t, m') \mid m, m' \in R_N(m_0), t \in T, m[t \succ m'\}.$$

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Section 12.2 Control Patterns

- eS-nets can be used to model causal dependencies; for modelling temporal aspects extensions of the formalism are required.
- Whenever between some transitions there are no causal dependencies, the transitions are called *concurrent*; concurrency is a prerequisite for parallelism.

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Some typical causalities

Sequence



Distributed Systems Part 2

Transactional Distributed Systems

Advanced Information Systems, SS 2011

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AND-join, OR-join, AND-split, OR-split



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OR-Split with regulation



Distributed Systems Part 2

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OR-Join with regulation



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A eS-Net with concurrency



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