Chapter 7: Modeling and Analysis of Distributed Applications

### Petri-Nets

- Petri-nets are abstract formal models capturing the flow of information and objects in a way which makes it possible to describe distributed systems and processes at different levels of abstraction in a unified language.

- Petri-nets have the name from their inventor Carl Adam Petri, who introduced this formalism in his PhD-thesis 1962.
Processing of complaints: informal description.
Complaints processing: formal Petri-net orchestration.¹

Complaints processing: more than one complaint
Complaints processing: how to distinguish complaints
Complaints processing: keeping things together
### Petri-nets

Petri-nets model system dynamics.
- Activities trigger state transitions,
- activities impose control structures,
- applicable for modelling discrete systems.

### Benefits

- Uniform language,
- can be used to model sequential, causal independent (concurrent, parallel, nondeterministic) and monitored exclusive activities.
- open for formal analysis, verification and simulation,
- graphical intuitive representation.

The name *Petri-net* denotes a variety of different versions of nets - we will discuss the special case of *System Nets* following the naming introduced by W. Reisig.
## Section 7.1 Elementary System Nets

### Basic elements of an elementary System Net (eS-Net)

- System states are represented by *places*, graphically circles or ovals.
- A place may be marked by an arbitrary number of *tokens* graphically represented by black dots.
- System dynamics is represented by *transitions*, graphically rectangles.
- *Transitions* represent activities (events) and the causalities between such activities (events) are represented by edges.
- *Multiplicities* represent the consumption, respectively creation of resources which are caused by the *occurrence* of activities.
3-Philosopher-Problem

\( b_j \): philosopher starts eating; \( e_j \): philosopher stops eating; 
\( i_j \): philosopher is eating; \( g_j \): fork on the desk; 
\( 1 \leq j \leq 3 \).
A transition *may* occur when certain conditions with respect to the markings of its directly connected places are fulfilled; the *occurrence* of a transition - also called its *firing* - effects the markings of its directly connected edges, i.e. has local effects.

The *surrounding* of a transition $t$ is given by $t$ and all its directly connected places:

$s_1, \ldots, s_k$ are called *preconditions* (*pre-places*), $s_{k+1}, \ldots, s_n$ *postconditions* (*post-places*).

A place which is pre- and post-place at the same time is called a *loop*. 
A net is given as a triple \( N = (P, T, F) \), where

- \( P \), the set of places, and \( T \), the set of transitionen, are non-empty disjoint sets,
- \( F \subseteq (P \times T) \cup (T \times P) \), is the set of directed edges, called flow relation, which is a binary relation such that \( \text{dom}(F) \cup \text{cod}(F) = P \cup T \).

Let \( N = (P, T, F) \) be a net and \( x \in P \cup T \).

\[
x F := \{ y \mid (x, y) \in F \}
\]
\[
F x := \{ y \mid (y, x) \in F \}
\]

For \( p \in P \), \( p F \) is the set of post-transitions of \( p \); \( F p \) is the set of pre-transitions of \( p \).
For \( t \in T \), \( t F \) is the set of post-places of \( t \); \( F t \) is the set of pre-places of \( t \).
Let $N = (P, T, F)$ be a net. Any mapping $m$ from $P$ into the set of natural numbers $\text{NAT}$ is called a *marking* of $P$.

A mapping $P \rightarrow \text{NAT} \cup \{\omega\}$ is called *$\omega$-marking*. $\omega$ represents an infinitely large number of tokens.

Arithmetic of $\omega$:

$$\omega - n = \omega, \omega + n = \omega, n \cdot \omega = \omega, 0 \cdot \omega = 0, \omega > n$$

where $n \in \text{NAT}, n > 0$.

A *marking* represents a possible system state.
A eS-Net is given as $N = (P, T, F, V, m_0)$, where

- $(P, T, F)$ a net,
- $V : F \rightarrow \text{NAT}^+$ a multiplicity,
- $m_0$ a marking called initial marking.

$N$ is called ordinary eS-Net, whenever $V(f) = 1$, $\forall f \in F$. 
A transition may fire once it is enabled.

Let $N = (P, T, F, V, m_0)$ a eS-Net, $m$ a marking and $t \in T$ a transition.

- $t$ is enabled at $m$, if for all pre-places $p \in Ft$ there holds:
  \[ m(p) \geq V(p, t). \]

- Whenever $t$ is enabled at $m$, then $t$ may fire at $m$. Firing $t$ at $m$ transforms $m$ to $m'$, $m[t \triangleright m']$, in the following way:

\[
m'(p) := \begin{cases} 
m(p) - V(p, t) + V(t, p) & \text{falls } p \in Ft, p \in tF, \\
m(p) - V(p, t) & \text{falls } p \in Ft, p \notin tF, \\
m(p) + V(t, p) & \text{falls } p \notin Ft, p \in tF, \\
m(p) & \text{sonst.}
\end{cases}
\]
Transitions and markings in terms of vectors

Let places in $P$ be linearly ordered.

- Markings of a net can be considered as vectors of nonnegative integers of dimension $|P|$, called place-vectors.

- Transitions $t$ can be characterized as vectors of nonnegative integers of dimension $|P|$, called transition vectors $\Delta t, t^+, t^-$:

Let $N = (P, T, F, V, m_0)$ a eS-Net, $p \in P$ and $t \in T$.

\[
t^+(p) := \begin{cases} 
V(t, p) & \text{if } p \in tF, \\
0 & \text{sonst.}
\end{cases}
\]

\[
t^-(p) := \begin{cases} 
V(p, t) & \text{if } p \in Ft, \\
0 & \text{sonst.}
\end{cases}
\]

\[
\Delta t(p) := t^+(p) - t^-(p).
\]
Place and transition vectors at work:

- \( m \leq m' \), if \( m(p) \leq m'(p) \) for \( \forall p \in P \),
- \( m < m' \), if \( m \leq m' \), however \( m \neq m' \).
- \( t \) is enabled at \( m \) iff \( t^- \leq m \),
- \( m \succ m' \) iff \( t^- \leq m \) and \( m' = m + \Delta t \).
Reachability

Let $N = (P, T, F, V, m_0)$ a eS-Net.

We denote $W(T)$ the set of words with finite length over $T$; $\epsilon \in W(T)$ is called the *empty word*.

The length of a word $w \in W(T)$ is given by $l(w)$. We have $l(\epsilon) = 0$.

Let $m, m'$ be markings of $P$ and $w \in W(T)$. We define a relation $m[w \succ m']$ inductively:

- $m[\epsilon \succ m']$ iff $m = m'$,
- Let $t \in T, w \in W(T)$. $m[wt \succ m']$ iff $\exists m'' : m[w \succ m''], m''[t \succ m']$.

The *reachability relation* $[\succ]$ of $N$ is defined by

$$m[\succ m'] \text{ iff } \exists w : w \in W(T), m[w \succ m'];$$

$m'$ is reachable from $m$ in $N$. 
### 7. Petri-Nets

#### 7.1. Elementary System Nets

- \( R_N(m) := \{ m' \mid m \ast \triangleright m' \} \), the set of markings reachable from \( m \) by \( N \),
- \( L_N(m) := \{ w \mid \exists m' : m \triangleright m' \} \), the set of all words representing firing sequences of transitions of \( N \) starting at \( m \),
- \( \Delta w := \sum_{i=1}^{n} \Delta t_i \), where \( w = t_1 t_2 \ldots t_n \).

### Results

- \( \ast \triangleright \) is reflexive and transitive.
- \( m \triangleright m' \Rightarrow (m + m^\ast) \triangleright (m' + m^\ast), \forall m^\ast \in NAT^{\mid P\mid} \). (Monotony)
- \( m \triangleright m' \Rightarrow m' = m + \Delta w. \)
Reachability graph

Let $N = (P, T, F, V, m_0)$ a eS-Net. The *Reachability graph* of $N$ is a directed graph $EG(N) := (R_N(m_0), B_N)$; $R_N(m_0)$ is the set of nodes and $B_N$ is the set of annotated edges as follows:

$$B_N = \{(m, t, m') | m, m' \in R_N(m_0), t \in T, m[t \succ m']\}.$$
Exercise: Give the reachability graph of the following eS-Net:

\[ R_N(m_0) = \{ (1, 0, 0, 0), (1, 1, 0, 0), (1, 2, 0, 0), (1, 3, 0, 0), \ldots, \\
(0, 0, 1, 0), (0, 1, 1, 0), (0, 2, 1, 0), (0, 3, 1, 0), \ldots, \\
(0, 0, 1, 1), (0, 1, 1, 1), (0, 0, 1, 2), (0, 2, 1, 1), (0, 1, 1, 2), (0, 0, 1, 3), \ldots \} \]

\[ L_N(m_0) = \{ \epsilon, t_1, t_1 t_1, t_1 t_1 t_1, \ldots, \\
t_2, t_1 t_2, t_1 t_1 t_2, t_1 t_1 t_1 t_2, \ldots, \\
t_1 t_2 t_3, t_1 t_1 t_2 t_3, t_1 t_1 t_2 t_3 t_3, t_1 t_1 t_2 t_3 t_3 t_3, t_1 t_1 t_1 t_2 t_3 t_3 t_3, \ldots \} \]
Section 7.2 Control Patterns

- eS-nets can be used to model *causal dependencies*; for modelling temporal aspects extensions of the formalism are required.

- Whenever between some transitions there are no causal dependencies, the transitions are called *concurrent*; concurrency is a prerequisite for parallelism.
Some typical causalities

### Sequence

![Sequence diagram]

### Iteration

![Iteration diagram]
AND-join, OR-join, AND-split, OR-split

AND-join

AND-split

OR-join

OR-split
OR-Split with regulation
OR-Join with regulation
A eS-Net with concurrency
Section 7.3 Analysis

Boundedness

Let $N = (P, T, F, V, m_0)$ be a eS-Net, $m$ a marking, $p \in P$.

- Let $k \in \mathbb{N}^+$. $p$ is called $k$-bounded, if for each marking $m'$ there holds:

  $$m' \in R_N(m_0) \Rightarrow m'(p) \leq k.$$

- $p$ is called bounded, if $p$ $k$-bounded for some $k \in \mathbb{N}^+$.  

- $N$ is called bounded ($k$-bounded), if each place is bounded ($k$-bounded).

- A eS-net is called safe, if it is 1-bounded. Places of a bounded net may be interpreted as boolean conditions.
Theorem

Let $N = (P, T, F, V, m_0)$ be a eS-Net. $N$ is unbounded, i.e. not bounded, iff there exist $w \in W(T)$, $m, m' \in R_N(m_0)$, such that $m[w \succ m'$ and $m' > m$.

Proof $\Leftarrow$

Let $w \in W(T)$, $m, m' \in R_N(m_0)$, such that $m[w \succ m'$ and $m' > m$. It holds

$$m[w \succ m'[w \succ m''[w \succ m''' \ldots,$$

where $m < m' < m'' < m''' < \ldots$.

Thus there must exist at least one unbounded place.
To proof ⇒ we first proof:

**Lemma**

For each infinite sequence of markings \((m_i)\) of markings there exists an infinite subsequence \((m'_j)\), which is weakly monotonic, i.e. \(l < k\) implies \(m'_l \leq m'_k\).

To prove the Lemma, first extract an infinite subsequence for which weak monotonicity holds for the first components of its markings. Then extract from that subsequence an infinite subsequence for which weak monotonicity holds for the second components of its markings, etc.
Proof ⇒

- Consider the reachability graph $EG(N)$, which has an infinite number of nodes. Starting from $m_0$ there exist a directed path to each node of the graph. Because of the finite number of transitions, each node has only a finite number of direct successors.

- Thus, at $m_0$ there start an infinite number of paths without cycles, however only a finite number of edges. Therefore, one of these edges must be part of infinitely many paths. Let $m_0 \rightarrow m_1$ be one such edge.

- The same argument can be applied w.r.t. $m_1$ such that we get $m_0 \rightarrow m_1 \rightarrow m_2$, where $m_1 \rightarrow m_2$ is part of an infinite number of paths.

- The above construction can be repeated infinitely many times. Therefore there exists an infinite sequence of markings $(m_i)$ of pairwise distinct markings, such that $m_k$, $m_l$, $0 \leq k \leq l$ implies:

$$m_0[*\succ m_k[*\succ m_l.$$ 

because of the Lemma there exists an infinite weakly monotonic subsequence $(m_j')$ von $(m_i)$. Let $m_1'$, $m_2'$ two successive elements. From construction we have $m_0[*\succ m_1'[*\succ m_2'$, $m_1' \leq m_2'$ and even $m_1' < m_2'$.
Reachability

Let \( N = (P, T, F, V, m_0) \) be a eS-Net, \( m \in \mathbb{N}^{|P|} \) a marking. The decision problem:

\[
m \in R_N(m_0)\
\]

is called reachability-problem.

The reachability problem is decidable, however even for bounded nets hyperexponential.
Coverability

Let $N = (P, T, F, V, m_0)$ be a eS-Net and let $m, m'$ be markings of $N$.

- If $m \leq m'$, then $m'$ covers $m$, respectively, $m$ is covered by $m'$.
- $m$ is called coverable in $N$, if there exists a reachable marking $m'$ which covers $m$.

Consequence: Whenever a marking is not coverable w.r.t. some eS-Net $N$, it is not reachable in $N$.

Give examples.
Coverability Graph

Let \( N = (P, T, F, V, m_0) \) a eS-Net. The Coverability Graph of \( N \) is given by \( CG(N) := (R, B) \) as follows:

- **inductive definition of an auxiliary tree \( T(N) \):**
  The values of the nodes in \( T(N) \) are \( \omega \)-markings of \( N \). The value of the root node \( r \) is \( m_0 \). Let \( m \) be the value of some node \( n \) of \( T(N) \), \( t \in T \), and \( m[t > m'] \).
  - Whenever on the path from the root \( r \) to \( n \) there exists a node \( n'' \) with value \( m'' \) such that \( m'' < m' \), then update \( m' \) by \( m'(p) := \omega \) for all places \( p \) with \( m''(p) < m'(p) \).
  - Introduce a new successor node \( n' \) of \( n \) with value \( m' \) and mark the edge from \( n \) to \( n' \) by \( t \).
  - If there already exists another node in the tree with the same value \( m' \), node \( n' \) is not considered any further.

- A coverability graph is derived from a coverability tree by taking the values of the nodes in the tree as nodes in the graph.
Give a coverability tree.
A eS-net with two different coverability graphs.
Two eS-Nets with identical coverability graphs.
Theorem

The coverability graph $CG(N) = (R, B)$ of a eS-net $N$ is finite.

Proof:
Assume $CG(N)$ is not finite. Then it contains an infinite number of nodes. Thus there exists an infinite, weakly monotonic sequence of $\omega$-markings, i.e. values of the nodes in the tree. Because of the construction of the auxiliary tree $T(N)$, such an infinite sequence cannot exist, as we can introduce $\omega$ only a finite number of times.
To test the reachability of a certain marking we may first test its coverability and then try to find a firing sequence which confirms its reachability.

Is marking \( m = (0, 3, 1, 3) \) reachable?

Yes, using the word \( w = t_1^6 t_2 t_3^3 \).
Live, dead and deadlockfree

Let $N = (P, T, F, V, m_0)$ a eS-Net.

- A marking $m$ is called **dead** in $N$, if there is no $t \in T$ which is enabled at $m$.
- A transition $t$ is called **dead** at marking $m$, if there is no marking reachable from $m$, such that $t$ is enabled.

If $t$ dead at $m_0$, then $t$ is called dead in $N$.

- A transition $t$ is called **live** at marking $m$, if for any reachable marking from $m$ it holds that $t$ is not dead.
  If $m = m_0$, then $t$ is called **live** in $N$.

- A marking $m$ is called **live** in $N$ if all transitionen $t \in T$ are **live** in $m$. If $m = m_0$ then $N$ is called **live**.
- $N$ is called **deadlockfree**, if no dead marking is reachable.

---

Note: whenever a transition is dead at some $m$, then it is not live at $m$.

However, the other direction does not hold.
Firing the word $t_3t_1t_2$ results in a dead marking $(0, 0)$. The coverability graph does not indicate this!

Liveness cannot be tested by inspection of the coverability graph.

Do there exist other techniques for analysis?
### Section 7.4 Invariants

#### Basics

- A Petri-net invariant is a property of a Petri-net, which holds for any marking, respectively transition word, of the net.
- We study place- and transition-invariants, which are based on a matrix representation of a net, respectively vector representation of markings and transitions.

#### Incidence Matrix

- Let $N = (P, T, F, V, m_0)$ a eS-Net, $T = \{t_1, \ldots, t_n\}$, $P = \{p_1, \ldots, p_m\}$, $n, m \geq 1$.
- A vector of dimension $n$ ($m$) is called $T$- ($P$-)vector.
- For any $t \in T$, $\Delta t$ can be represented as a column $P$-vector.
- The *incidence matrix* of $N$ is given as a $m \times n$-matrix $C = (\Delta t_1, \ldots, \Delta t_n)$, respectively $C = (c_{i,j})_{1 \leq i \leq m, 1 \leq j \leq n}$, where $c_{ij} := \Delta t_j(s_i)$. 

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Example

\[ C = \begin{pmatrix}
1 & -1 & 0 & 0 \\
-1 & -1 & 1 & 0 \\
0 & 2 & -1 & 0
\end{pmatrix} \]
- Incidence matrices are independent of concrete markings,
- In case of loops, information concerning multiplicities is lost.

**Parikh-Vektor**

The transpose of a vector $x$, resp. matrix $C$ is denoted by $x^\top$, bzw. $C^\top$.

The *Parikh-Vektor* $\bar{q}$ of some $q \in W(T)$ is a column $T$-vector, $n = |T|$, defined as follows:

$$\bar{q} : T \to NAT,$$

where $\bar{q}(t)$ is the number of occurrences of $t$ in $q$. 
State Equation

Let \( q \in W(T) \) and \( m, m' \) markings.

If \( m \models q \succ m' \), then
\[
\sum_{t \in \mathcal{T}} (\bar{q}(t) \cdot \Delta t) = C \cdot \bar{q} = \Delta q.
\]

Moreover, as \( m \models q \succ m' \), we have

\[ m' = m + \Delta q^\top. \]

The equation:
\[ m' = m + (C \cdot \bar{q})^\top \]

is called state equation.

The system of linear equations given by
\[ C \cdot x = (m' - m)^\top \]

has an integer nonnegative solution \( x \).
however the following does not hold in general:

If $C \cdot x = (m' - m)^\top$ has an integer nonnegative solution then

$$\exists q \in W(T) : m[q \succ m'],$$

i.e., the reachability problem cannot be solved, in general.

Example

Let $m = (1, 0, 0)$, $m' = (0, 0, 1)$.
$x = (0, 1, 1, 0)^\top$ is a solution for $C \cdot x = (m' - m)^\top$, however we cannot find a word which can be fired at $m$. 
Theorem

Let $N$ be a eS-Net and $\Delta$ a $P$-vector. There exists a marking $m^*$ and a word $q \in W(T)$, such that $m^*[q \succ (m^* + \Delta)]$, iff $C \cdot x = \Delta^\top$ has an integer nonnegative solution.

Proof:

"$\Rightarrow$" : trivial.

"$\Leftarrow$" : Let $m^* := \sum_{t \in T} x(t) \cdot t^-$. 
Corollary

Let $N = (P, T, F, V, m_0)$ be a eS-Net. There exists a marking $m^*$ such that
$N = (P, T, F, V, m^*)$ unbounded, iff $C \cdot x > 0$ has an integer nonnegative solution.

Useful application of the corollary:

If there does not exist an integer nonnegative solution for $C \cdot x > 0$, then for any initial
marking, $N$ is bounded.
Transition-Invariants (T-Invariants)

Let $N = (P, T, F, V, m_0)$ be a eS-Net.

- Any nontrivial integer solution $x$ of the homogenous linear equation system $C \cdot x = 0$ is called transition-invariant (T-invariant) of $N$.
- A T-invariant $x$ is called **proper**, if $x \geq 0$.
- A T-invariant $x$ is called **realizable** in $N$, if there exists a word $q \in W(T)$ with $\bar{q} = x$ and a reachable marking $m$ such that $m[q \succ m]$.
- $N$ is called **covered with T-invariants**, if there exists a T-invariant $x$ of $N$ with all components positive, i.e. greater than 0.

Proper T-invariants denote *possible* cycles of the reachability graph - realizable T-invariants denote cycles which indeed may occur.
Example

T-invariants of

\[
x = \lambda_1 \begin{pmatrix} 1 \\ 1 \\ 2 \\ 0 \end{pmatrix} + \lambda_2 \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}
\]

are as follows:

where \( \lambda_1, \lambda_2 \) integers.
Theorem

Let $N = (S, T, F, V, m_0)$ be a eS-Net. If there exists a marking $m$, such that $N$ live and bounded at $m$, then $N$ covered by T-invariants.

Proof: Let $N$ live and bounded at some $m$.

As $N$ is live at $m$, there exists a word $q_1 \in L_N(m)$, which contains all transitions in $T$ and the marking $m + \Delta q_1$ is reachable from $m$.

Moreover, $N$ is live at $m + \Delta q_1$ as well. Therefore, there exits a word $q_2 \in L_N(m)$, which contains all transitions in $T$ and $N$ is live at the marking $m + \Delta q_1 q_2$.

There exists an infinite sequence of markings $(m_i)$, where $m_i := m + \Delta q_1 \ldots q_i$, such that:

$$m[q_1 \succ m_1[q_2 \succ m_2 \ldots m_i[q_{i+1} \succ m_{i+1} \ldots$$

As $N$ is bounded at $m$, there is only a finite number of markings which are reachable. Therefore, there exist $i, j \in \mathbb{N}^+$ such that $m_i = m_j$. Thus

$$m_i[q_{i+1} \ldots q_j \succ m_j = m_i$$

As all these $q_i$ mention all transitions, we finally conclude

$$x = \bar{q}_{i+1} + \ldots + \bar{q}_j$$

is a T-Invariant which covers $N$. 
Useful application of the theorem:
Whenever $N$ is not covered by T-invariants, then for every marking it holds $N$ not live or not bounded.
Place-Invariants (P-Invariants)

Let $N = (P, T, F, V, m_0)$ be a eS-Net.

- Any nontrivial integer solution $y$ of the homogeneous linear equation system $y \cdot C = 0$ is called place-invariant (P-invariant) of $N$.
- A P-invariant $y$ is called proper P-invariant, if $y \geq 0$.
- $N$ is called covered with P-invariants, if there exists a P-invariant $y$ with all components positive, i.e. greater than 0.

If $y$ is a P-invariant, then for any marking $m$ the sum of the number of tokens on the places $p$ is invariant with respect to the firing of the transitions weighted by $y(p)$.
Example

P-invariants of

\[
\begin{bmatrix}
1 \\
1 \\
1
\end{bmatrix}
\]

are as follows:

\[y^T = \lambda \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}\]

where \(\lambda\) is an integer.
Theorem

Let $N = (P, T, F, V, m_0)$ a eS-Net and let $y$ a P-invariant of $N$. Then:

$$m \in R_N(m_0) \Rightarrow y \cdot m^\top = y \cdot m_0^\top.$$ 

Proof:
Assume $m_0[ q \triangleright m$. Then $m = m_0 + (C \cdot \bar{q})^\top$ and also:

$$y \cdot m^\top = y \cdot m_0^\top + y \cdot (C \cdot \bar{q}) =
= y \cdot m_0^\top + (y \cdot C) \cdot \bar{q} = y \cdot m_0^\top + 0 \cdot \bar{q} = y \cdot m_0^\top.$$
Corollary:

- Let \( y \) be a \( P \)-invariant of \( N \), \( m \) marking.
  \[ y \cdot m^\top \neq y \cdot m_0^\top \Rightarrow m \not\in R_N(m_0). \]

- Let \( y \) be a proper \( P \)-invariant of \( N \). Let \( p \in P \) such that \( y(p) > 0 \).
  Then, for any initial marking, \( p \) is bounded.

  Proof: \( y \cdot m_0^\top = y \cdot m^\top \geq y(p) \cdot m(p) \geq m(p). \)

- Let \( N \) be covered by \( P \)-invariants. \( N \) is bounded for any initial marking.
Note, the following net is bounded for any initial marking, however does not have a P-invariant:

![Diagram of a Petri-net with a single place p and a transition t connecting it]  

P-invariants allow sufficient tests for non-reachability and boundedness.
Example: Prove freedom from deadlocks.

Initial marking is given by \( m_0 = (2, 0, 0, 0, 1, 1, 1) \). Assume there exist a dead marking \( m, m_0[q \succ m] \). Then it must hold \( m(p_1) = m(p_2) = m(p_3) = 0 \). Because of \( Y_4 \) it follows \( m(p_0) = 2 \). As \( m \) dead it follows \( m(p_4) = m(p_5) = m(p_6) = 0 \). However this contradicts \( Y_1 m_0 = Y_1 m \).
Sometimes when modelling we would like to fix an upper bound for the number of tokens in a place.

- Let \( N = (P, T, F, V, m_0) \) be a eS-Net, \( c \) a \( \omega \)-marking of \( P \) and let \( m_0 \leq c \). \((N, c)\) is called eS-Net with capacities. \( c(p), p \in P \) is called capacity of \( p \).

- For eS-nets with capacities the notion of being enabled is adapted:

  \[ \text{a transition } t \in T \text{ is enabled at marking } m, \text{ if } t^- \leq m \text{ and } m + \Delta t \leq c. \]

- Capacities graphically are labels of places - no label means capacity \( \omega \).
Any eS-net with capacities can be simulated by a eS-Net without capacities.

**Construction**

- Let $p$ a palce with capacity $k = c(p), k \geq 1$. Let $p^{co}$ be the complementary place of $p$ which is assigned the initial marking $k - m_0(p)$.
- Whenever for a transition $t$ we have $\Delta t(p) > 0$, we introduce an arc from $p^{co}$ to $t$ with multiplicity $\Delta t(p)$;
  whenever $\Delta t(p) < 0$, we introduce an arc from $t$ to $p^{co}$ with multiplicity $-\Delta t(p)$. 
A eS-Net with capacities and its simulation by a bounded eS-Net.

\[ N_1(k = 4): \]

\[ N_2:\]
Section 7.6 S-Nets with Colors

- eS-Nets in practice may become huge and difficult to understand.
- Sometimes such nets exhibit certain regularities which give rise to questions how to reduce the size of the net without losing modeling properties.
What about a $n$-philosopher problem with $n \gg 3$?

Why not introduce tokens with individual information?
Abstraction 5-philosopher problem

Note: the intention of the marking shown only is to demonstrate „individual“ tokens.

What about being enabled and firing?
Colored System-Nets

A colored System-Net distinguishes different kinds of sorts for markings - the so called *colors* - and functions over these sorts which are used to label the edges of the net.

Generalizing eS-Nets, in a colored net a transition will be called enabled, if certain conditions are true, which are based on the functions which are assigned to the edges of the transitions surrounding.

Thus, we have colors, to characterize markings (*place colors*), and colors, to characterize the firing of transitions (*transition colors*).

As a marking of a place now can be built out of different kind of tokens, we introduce multisets.

- Let $A$ be a set. A *multiset* $m$ over $A$ is given by a mapping $m : A \rightarrow \text{NAT}$.
- Let $a \in A$. If $m[a] = k$ then there exist $k$ occurrences of $a$ in $m$.
- A multiset oftenly is written as a (formal) sum, e.g. $[\text{Apple, Apple, Pear}]$ is written as $2 \cdot \text{Apple} + 1 \cdot \text{Pear}$. 

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A colored version of the 3-Philosopher-Problem

Colors

\[ C(g) = \{g_1, g_2, g_3\}, \quad C(i) = \{ph_1, ph_2, ph_3\} \quad \text{place colors} \]
\[ C(b) = \{ph_1, ph_2, ph_3\}, \quad C(e) = \{ph_1, ph_2, ph_3\} \quad \text{transition colors} \]

Functions

\[ ID(ph_j) := 1 \cdot ph_j, \quad 1 \leq j \leq 3 \]
\[ RL(ph_j) := \begin{cases} 
1 \cdot g_1 + 1 \cdot g_3 & \text{if } j = 1, \\
1 \cdot g_{j-1} + 1 \cdot g_j & \text{if } j \in \{2, 3\}. 
\end{cases} \]
Multiplicities

A *multiplicity* assigned to an edge between a place $p$ and a transition $t$ is a mapping from the set of transition colors of $t$ into the set of multisets over the colors of $p$.

In the example:

$$V(b, i) = V(i, e) = ID, \ V(g, b) = V(e, g) = RL,$$

where:

$$ID(ph_j) := 1 \cdot ph_j, 1 \leq j \leq 3$$

$$RL(ph_j) := \begin{cases} 1 \cdot g_1 + 1 \cdot g_3 & \text{if } j = 1, \\ 1 \cdot g_{j-1} + 1 \cdot g_j & \text{if } j \in \{2, 3\}. \end{cases}$$

$ID$ denotes the identity mapping.

Marking

Markings are multisets over the respective place colors.

In the example:

$$m_0(p) := \begin{cases} 1 \cdot g_1 + 1 \cdot g_2 + 1 \cdot g_3 & \text{if } p = g, \\ 0 & \text{otherwise.} \end{cases}$$
A colored Net $CN = (P, T, F, C, V, m_0)$ is given by:

- A net $(P, T, F)$.
- A mapping $C$ which assigns to each $x \in P \cup T$ a finite nonempty set $C(x)$ of colors.
- Mapping $V$ assigns to each edge $f \in F$ a mapping $V(f)$.

Let $f$ be an edge connecting place $p$ and transition $t$. $V(f)$ is a mapping from $C(t)$ into the set of multisets over $C(p)$.

- $m_0$ is the initial marking given by a mapping which assigns to each place $p$ a multiset $m_0(p)$ over $C(p)$. 

Let $CN = (P, T, F, C, V, m_0)$ be a colored System-Net.

▶ A marking $m$ of $P$ is mapping which assigns to each place $p$ a multiset $m(p)$ over $C(p)$.

▶ A transition $t$ is enabled in color $d \in C(t)$ at $m$, if for all pre-places $p \in Ft$ there holds:

$$V(p, t)(d) \leq m(p).$$

▶ Assume $t$ is enabled in color $d$ at marking $m$. Firing of $t$ in color $d$ transforms $m$ to a marking $m'$:

$$m'(p) := \begin{cases} 
    m(p) - V(p, t)(d) + V(t, p)(d) & \text{if } p \in Ft, \\
    m(p) - V(p, t)(d) & \text{if } p \in Ft,, \\
    m(p) + V(t, p)(d) & \text{if } p \notin Ft,, \\
    m(p) & \text{otherwise.}
\end{cases}$$
Fold and Unfold of a Colored System-Net

Folding

By folding of a eS-Net we can reduce the number of places and transitions; places and transitions are represented by appropriate place and transition colors, on which certain functions defining the multiplicities are defined.

Let $N = (P, T, F, V, m_0)$ a eS-Net. A folding is defined by $\pi$ and $\tau$:

- $\pi = \{q_1, \ldots, q_k\}$ a (disjoint) partition of $P$,
- $\tau = \{u_1, \ldots, u_n\}$ a (disjoint) partition of $T$. 

Two special cases

Call $GN(\pi, \tau) := (P', T', F', C', V', m'_0)$ the result of folding.

- All elements of $\pi, \tau$ are one-elementary:
  
  $\Rightarrow N$ and $GN(\pi, \tau)$ are isomorph,

- $\pi, \tau$ contain only one element:
  
  $\Rightarrow |P'| = |T'| = 1,$ ”the model is represented by the labellings”.
3-Philosopher-Problem

Folding $\pi = \{\{g_1, g_2, g_3\}, \{i_1, i_2, i_3\}\}$, $\tau = \{\{b_1, b_2, b_3\}, \{e_1, e_2, e_3\}\}$.

Colors from folding:
$C(g) = \{g_1, g_2, g_3\}$, $C(i) = \{i_1, i_2, i_3\}$, $C(b) = \{b_1, b_2, b_3\}$, $C(e) = \{e_1, e_2, e_3\}$

Multiplicities: $ID$, $RL$ analogously to previous version.
3-Philosopher-Problem?

\[
\pi = \{P\}, \quad \tau = \{T\}:
\]
\[
S' = \{s'\}, \quad T' = \{t'\},
\]
\[
C(s') = \{g_1, g_2, g_3, i_1, i_2, i_3\},
\]
\[
C(t') = \{b_1, b_2, b_3, e_1, e_2, e_3\},
\]
\[
m_0(s') = g_1 + g_2 + g_3.
\]

\[
V'(s', t')(t) = \begin{cases} 
  g_1 + g_3 & \text{falls } t = b_1, \\
  g_1 + g_2 & \text{falls } t = b_2, \\
  g_2 + g_3 & \text{falls } t = b_3, \\
  i_1 & \text{falls } t = e_1, \\
  i_2 & \text{falls } t = e_2, \\
  i_3 & \text{falls } t = e_3,
\end{cases}
\]

\[
V'(t', s')(t) = \begin{cases} 
  g_1 + g_3 & \text{falls } t = e_1, \\
  g_1 + g_2 & \text{falls } t = e_2, \\
  g_2 + g_3 & \text{falls } t = e_3, \\
  i_1 & \text{falls } t = b_1, \\
  i_2 & \text{falls } t = b_2, \\
  i_3 & \text{falls } t = b_3.
\end{cases}
\]
Given \( \pi = \{q_1, \ldots, q_k\} \), \( \tau = \{u_1, \ldots, u_n\} \).

The folding \( GN(\pi,\tau) := (P', T', F', C', V', m'_0) \) of \( N \) is defined as follows:

\[
\begin{align*}
\text{▶ } & P' := \{p'_1, \ldots, p'_k\}; \ T' := \{t'_1, \ldots, t'_n\}, \\
\text{▶ } & C'(p'_i) = q_i \text{ für } i = 1, \ldots, k; \ C'(t'_j) = u_j \text{ für } j = 1, \ldots, n, \\
\text{▶ } & F' := \{(p', t') \mid C'(p') \times C'(t') \cap F \neq \emptyset\} \cup \{(t', p') \mid C'(t') \times C'(p') \cap F \neq \emptyset\}, \\
\text{▶ } & f' = (p', t') \in F': V'(f') \text{ is defined } (t \in C'(t')):\ \\
& \quad V'(f')(t) = \sum_{p \in C'(p')} t^-(p) \cdot p, \\
\text{▶ } & f' = (t', p') \in F': V'(f') \text{ is defined } (t \in C'(t')):\ \\
& \quad V'(f')(t) = \sum_{p \in C'(p')} t^+(p) \cdot p, \\
\text{▶ } & m'_0(p') := \sum_{p \in C'(p')} m_0(p) \cdot p.
\end{align*}
\]
Unfolding

Let $\text{GN} = (P, T, F, C, V, m_0)$ a CN-Net.

The Unfolding of $\text{GN}$ is a eS-Net $\text{GN}^* := (P^*, T^*, F^*, V^*, m^*_0)$ given as follows:

- $P^* := \{(p, c) \mid p \in P, c \in C(p)\}$,
- $T^* := \{(t, d) \mid t \in T, d \in C(t)\}$,
- $F^* := \{((p, c), (t, d)) \mid (p, t) \in F, V(p, t)(d)[c] > 0\} \cup\{(l, a) \mid (t, p) \in F, V(t, p)(d)[p] > 0\}$,
- $V^*((p, c), (t, d)) := V(p, t)(d)[c]$,
- $V^*((t, d), (p, c)) := V(t, p)(d)[c]$,
- $m^*_0(p, c) := m_0(p)[c]$. 

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Definition

Let $E$ be a certain property of a net, e.g. boundedness, liveness, or reachability.

A CS-Net $GN$ has property $E$, whenever its unfolding $GN^*$ has property $E$.

Analysis of colored System Nets

- Analyse unfolding:
  
  Advantage: Methods exist,
  
  Pitfall: Unfoldings may be huge eS-Nets.

- Analyse colored net:
  
  - Reachability graph and coverability graph can be defined in analogous way to eS-Nets.
  
  - There exists a theory for invariants, as well.
  
  - Tools for simulation and analysis are available.